

Use of Hotelling's T^2 : Outlier Diagnostics in Mixtures

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Abstract

Given Gaussian observation vectors $[Y_1, \dots, Y_n]$ having a common mean and dispersion matrix, a pervading issue is to identify shifted observations of type $\{Y_i \rightarrow Y_i + \delta_i\}$. Conventional usage enjoins Hotelling's T_i^2 diagnostics, derived and applied under the mutual independence of $[Y_1, \dots, Y_n]$. Independence often fails, yet the need to identify outliers nonetheless persists. Accordingly, the present study reexamines T_i^2 under dependencies to include equicorrelations and more general matrices. Such dependencies are found in the analysis of calibrated vector measurements and elsewhere. In addition, mixtures of these distributions having star-shaped contours arise on occasion in practice. Nonetheless, the T_i^2 diagnostics are shown to remain exact in level and power for all such mixtures. Moreover, further matrix distributions, not necessarily having finite moments, are seen to generalize n -dimensional spherical symmetry to include non-Gaussian matrices of order $(n \times k)$ supporting T_i^2 . For these the use of T_i^2 remains exact in level. These findings serve to expand considerably the range of applicability of T_i^2 in practice, to include matrix Cauchy and other heavy tailed distributions intrinsic to econometric and other studies. Case studies serve to illuminate the methodology.

Keywords Outlying data, deletion diagnostics, dependent errors, Hotelling's T^2

1. Introduction

Let $Y_0 = [Y_1, \dots, Y_n]'$ comprise n vectors $\{Y_i' = [Y_{i1}, \dots, Y_{ik}]; 1 \leq i \leq n\}$ having identical means $E(Y_i') = \mu' = [\mu_1, \dots, \mu_k]$ and dispersion matrix $\{V(Y_i) = \Sigma; 1 \leq i \leq n\}$. The model is $\{Y_0 = \mathbf{1}_n \cdot \mu' + \mathcal{E}_0\}$, where $\mathcal{E}_0 = [\epsilon_{ij}]$ consists of random errors, and $E_0 = [e_{ij}]$ contains the ordinary observed residuals. The problem at issue, and of persistent concern to users, is whether shifts of type $\{Y_i \rightarrow Y_i + \delta_i\}$ in \mathbb{R}^k may have occurred. Numerous approaches have been advocated, to include graphics and numerical diagnostics. Selected references are listed subsequently; a recent survey is Rodrigues and Boente (2011). Prominent deletion diagnostics are modeled on Mahalanobis (1936) distance metrics in \mathbb{R}^k .

Under single-case deletions, the rows $[Y_i', \epsilon_i']$ are removed from $[Y_0, \mathcal{E}_0]$, retaining Y from $Y_0 = [Y', Y_i]'$ and e_i from $E_0 = [E', e_i]'$. For $k = 1$, with S_i^2 as the residual mean square, the R -Student statistics $t_i^2 = n e_i^2 / (n-1) S_i^2$ trace to Snedecor and Cochran (1968, page 157) in testing for a single shift $\{Y_i + \delta_i\}$; see also Beckman and Trussell (1974). Corresponding to t_i^2 for $k > 1$ are Hotelling's (1931) diagnostics T_i^2 given by

$$\left\{ T_i^2 = \frac{n e_i' S_i^{-1} e_i}{(n-1)}; 1 \leq i \leq n \right\} \quad (1)$$

where $(n-1)S_i = Y'Y$. In having exact and well documented normal-theory operating characteristics, these remain the diagnostics of choice for many users. Initially derived under normality and the mutual independence of $[Y_1, \dots, Y_n]$, these assumptions continue to validate the use of T_i^2 up to the present. For early developments see Caroni (1987), and more recently Barrett and Ling (1992) and Barrett (2003), together with references cited. Clearly independence often fails in practice, yet the need to identify outliers nonetheless persists.

As background, precedents for this study in the case $k = 1$ include t_i^2 and the diagnostics of Dixon (1950), Grubbs (1950), and Ferguson (1961) based on order statistics. As reassessed in Jensen and Ramirez (2015), all remain exact in level and power under dependent ensembles of distributions in \mathbb{R}^n , and for mixtures over these ensembles having star-shaped contours.

The *objectives* of this research are to extend those findings to include mixture distributions for Gaussian matrices $Y_0 = [Y_1, \dots, Y_n]'$ having dependent elements with the direct-product structure $V(Y_0) = \Omega \otimes \Sigma$, and for mixtures of these. Here Ω is taken as an equicorrelation matrix $\Omega(\rho)$ or the more general $\Omega(\xi)$ to be identified. In addition, left-spherical matrix

distributions serve to generalize the notion of spherical symmetry on \mathbb{R}^n , thereby to encompass matrix stable laws and Cauchy distributions. For the latter the use of T_i^2 nonetheless is seen to remain exact in level. These findings serve to expand considerably the range of applicability of T_i^2 in practice, to include heavy tailed distributions. Accordingly, normal-theory T_i^2 diagnostics are seen to be genuinely nonparametric.

Precedents for undertaking the mixtures and dependence structures of this study trace to Box and Tiao (1968) and Aitken and Wilson (1980), who modeled data from subsamples as Gaussian mixtures. Moreover, among other venues, calibrated data subject to errors of calibration often are equicorrelated under both direct and inverse calibration, as seen in Jensen and Ramirez (2009, 2012). The importance of heavy-tailed distributions in economics and finance is highlighted in Ibragimov *et al.* (2015). An outline of the study follows.

Preliminary developments are given in Section 2. The principal findings follow in Section 3, and some consequences of these are detailed through examples in Section 4. Critical supporting topics, to include essential matrix distributions, are attached for completeness as an Appendix.

2. Preliminaries

2.1 Notation

Spaces of note include the Euclidean n -space \mathbb{R}^n ; its positive orthant \mathbb{R}_+^n ; the real $(n \times k)$ matrices $\mathbb{F}_{n \times k}$; the symmetric $(n \times n)$ matrices \mathbb{S}_n ; and their positive definite varieties \mathbb{S}_n^+ . Vectors and matrices are set in bold type; the transpose, inverse, trace, and determinant of \mathbf{A} are \mathbf{A}' , \mathbf{A}^{-1} , $\text{tr}(\mathbf{A})$, and $|\mathbf{A}|$; \mathbf{I}_n is the $(n \times n)$ identity; $\text{Diag}(\mathbf{A}_1, \dots, \mathbf{A}_k)$ is a block-diagonal array; and $\mathbf{1}'_n = [1, \dots, 1] \in \mathbb{R}^n$ is the unit vector. The direct matrix product is $\mathbf{A} \otimes \mathbf{B} = [a_{ij}\mathbf{B}]$. An idempotent matrix of note is $\mathbf{B}_n = (\mathbf{I}_n - \frac{1}{n}\mathbf{1}_n\mathbf{1}'_n)$.

A random $\mathbf{Y} \in \mathbb{R}^n$ has distribution $\mathcal{L}(\mathbf{Y})$; the mean vector $\mathbf{E}(\mathbf{Y})$ and dispersion matrix $\mathbf{V}(\mathbf{Y}) = \mathbf{\Sigma}$, with variance $\text{Var}(\mathbf{Y}) = \sigma^2$ on \mathbb{R}^1 . Its density (*pdf*) and cumulative distribution function (*cdf*) are $g(\mathbf{y})$ and $G(\mathbf{y})$; and its characteristic function (*chf*) is $\phi_{\mathbf{Y}}(\mathbf{t})$. Specifically, $\mathcal{L}(\mathbf{Y}) = N_n(\boldsymbol{\mu}, \mathbf{\Sigma})$ is Gaussian in \mathbb{R}^n with mean vector $\boldsymbol{\mu}$ and dispersion matrix $\mathbf{\Sigma}$, whereas $\mathcal{L}(\mathbf{Y}_0) = N_{n \times k}(\mathbf{M}, \mathbf{\Omega} \otimes \mathbf{\Sigma})$ is Gaussian in $\mathbb{F}_{n \times k}$ with designated parameters. A random $\mathbf{W} \in \mathbb{S}_k^+$ is said to have the Wishart distribution $\mathbb{W}_k(\nu, \mathbf{\Sigma}, \boldsymbol{\Theta})$ of order k , with ν degrees of freedom, the scale parameters $\mathbf{\Sigma}$, and the noncentrality matrix $\boldsymbol{\Theta}$. Further details are supplied in Appendix A.1.

Distributions on \mathbb{R}_+^1 include $\chi^2(u; \nu, \sigma^2, \lambda)$ as chi-squared with argument u , having ν degrees of freedom, the scale parameter σ^2 , and noncentrality λ ; and Hotelling's (1931) $T_k^2(u; \nu, \lambda)$ of order k having ν degrees of freedom and noncentrality parameter λ . Moreover, $F(u; \nu_1, \nu_2, \lambda)$ is the noncentral Snedecor–Fisher F -distribution having ν_1 and ν_2 degrees of freedom, which increases stochastically with the noncentrality parameter λ . Identify $\{T_i^2 > c_\alpha\}$ as the conventional α -level rejection rule based on $T_k^2(u; \nu, 0)$.

2.2 The Model

We specialize from the model $\{\mathbf{Y}_0 = \mathbf{X}_0\mathbf{B} + \boldsymbol{\mathcal{E}}_0\}$ with $\mathbf{Y}_0 = [\mathbf{Y}_1, \dots, \mathbf{Y}_n]' \in \mathbb{F}_{n \times k}$, $\mathbf{X}_0 = [\mathbf{x}_1, \dots, \mathbf{x}_n]' \in \mathbb{F}_{n \times d}$ of rank $d < n$ with \mathbf{x}_i as design point i , and $\mathbf{B} = [\boldsymbol{\beta}_1, \dots, \boldsymbol{\beta}_k] \in \mathbb{F}_{d \times k}$. Under single-case deletions $\boldsymbol{\mathcal{E}}_0 = [\boldsymbol{\mathcal{E}}', \boldsymbol{\epsilon}_i']$ consists of random errors; $\mathbf{E}_0 = [\mathbf{E}', \mathbf{e}_i']$ are ordinary residuals; and $\mathbf{H}_n = \mathbf{X}_0(\mathbf{X}'_0\mathbf{X}_0)^{-1}\mathbf{X}'_0$.

Definition 1. In particular, we take $\{\mathbf{Y}_0 = \mathbf{1}_n \cdot \boldsymbol{\mu}' + \boldsymbol{\mathcal{E}}_0\}$ and $\mathbf{H}_n = \mathbf{1}_n\mathbf{1}'_n/n$ in keeping with the objectives of this study.

To continue, extended Gauss-Markov assumptions take $\mathbf{V}(\mathbf{Y}_0) = \mathbf{\Omega} \otimes \mathbf{\Sigma}$, where $\mathbf{\Omega}$ takes values $\mathbf{\Omega}(\rho)$ (equivalently $\mathbf{\Omega}(\theta)$) and $\mathbf{\Omega}(\boldsymbol{\xi})$ as in Section 2.3.

Assumptions A. The following hold for a model with a single shift.

A₁. $\mathbf{E}(\boldsymbol{\mathcal{E}}_0) = \mathbf{\Delta} = [\mathbf{O}', \boldsymbol{\delta}_i']$ with $\mathbf{O}(n-1 \times k)$ a matrix of zeroes such that $\mathbf{E}(\boldsymbol{\mathcal{E}}) = \mathbf{O}$ and $\mathbf{E}(\boldsymbol{\epsilon}_i) = \boldsymbol{\delta}_i$;

A₂. $\mathbf{V}(\boldsymbol{\mathcal{E}}_0) = \mathbf{\Omega} \otimes \mathbf{\Sigma}$ with $\mathbf{\Omega} \in \{\mathbf{\Omega}(\rho), \mathbf{\Omega}(\boldsymbol{\xi})\}$; and

A₃. $\mathcal{L}(\boldsymbol{\mathcal{E}}_0) = N_{n \times k}(\mathbf{\Delta}, \mathbf{\Omega} \otimes \mathbf{\Sigma})$ for $\mathbf{\Omega} \in \{\mathbf{\Omega}(\rho), \mathbf{\Omega}(\boldsymbol{\xi})\}$.

As in conventional deletion diagnostics, this represents a shift $\{\mathbf{Y}_i \rightarrow \mathbf{Y}_i + \boldsymbol{\delta}_i\}$ at the design point \mathbf{x}_i (now the index i) in \mathbf{X}_0 .

2.3 The Matrices Ξ

Validity in linear inference rests in part on the structure of dispersion matrices. Three cases are considered, namely $\mathbf{\Omega}(\theta)$, $\mathbf{\Omega}(\boldsymbol{\xi})$, and $\mathbf{\Omega}(\rho)$ where, for $\boldsymbol{\xi}' = [\xi_1, \dots, \xi_n]$, we have $\tau_1 = \xi_1 + \dots + \xi_n = n\bar{\xi}$ and $\tau_2 = \sum_{i=1}^n (\xi_i - \bar{\xi})^2$. Details follow, where

$$\alpha_1 = \frac{1}{2}[\tau_1 + (\tau_1^2 + 4n\tau_2)^{\frac{1}{2}}] \quad \text{and} \quad \alpha_n = \frac{1}{2}[\tau_1 - (\tau_1^2 + 4n\tau_2)^{\frac{1}{2}}]. \tag{2}$$

Lemma 1. (i) Let $\Omega(\theta) = \sigma^2(\mathbf{I}_n + \theta\mathbf{1}_n\mathbf{1}'_n)$; its eigenvalues are 1.0, with multiplicity $n-1$, and $1+n\theta$, so that $\Omega(\theta)$ is positive definite if and only if $\theta \in \Gamma_1 = \{\theta : \theta > -\frac{1}{n}\}$.

(ii) Let $\Omega(\xi) = \sigma^2(\mathbf{I}_n + \mathbf{1}_n\xi' + \xi\mathbf{1}'_n - \bar{\xi}\mathbf{1}_n\mathbf{1}'_n)$ with $\mathbf{0} \neq \xi \neq \theta\mathbf{1}_n$; its ordered eigenvalues are $\{\kappa_1 = 1 + \alpha_1, \kappa_2 = \dots = \kappa_{n-1} = 1, \kappa_n = 1 + \alpha_n\}$ as in (2.1); then $\Omega(\xi)$ is positive definite if and only if $\xi \in \Gamma_2 = \{\xi \in \mathbb{R}^n : \tau_1 > n\tau_2 - 1\}$.

(iii) Let $\Omega(\rho) = \sigma^2[(1-\rho)\mathbf{I}_n + \rho\mathbf{1}_n\mathbf{1}'_n]$, the equicorrelated case; then $\Omega(\rho)$ is positive definite if and only if $\rho \in \Gamma_3 = \{\rho : -\frac{1}{n-1} < \rho < 1\}$.

Proof. Details are given in Jensen (1996). ■

That $\Omega(\theta)$ and $\Omega(\rho)$ are equivalent follows on taking $\theta = \rho/(1-\rho)$, so that $\Omega(\theta) = \frac{1}{1-\rho}\Omega(\rho)$. Accordingly, the collections $\Xi_1 = \{\Omega(\theta); \theta \in \Gamma_1\}$, equivalently, $\Xi_1 = \{\Omega(\rho); \rho \in \Gamma_3\}$, and $\Xi_2 = \{\Omega(\xi); \xi \in \Gamma_2\}$, comprise ensembles of positive definite matrices, to be amalgamated as $\Xi = \Xi_1 \cup \Xi_2$. For further details see Jensen (1996).

2.4 Mixture Distributions

From Assumption A₁ let $\Lambda = \mathbf{1}_n \cdot \boldsymbol{\mu}' + \Delta$ and consider $g_{r \times k}(\mathbf{y}; \Lambda, \Omega \otimes \Sigma)$ in $\mathbb{F}_{r \times k}$ as the Gaussian density corresponding to $N_{r \times k}(\Lambda, \Omega \otimes \Sigma)$ as in Appendix A.1. These generate ensembles as Ω ranges over Ξ , namely

$$E_1 = \{g_{r \times k}(\mathbf{y}; \Lambda, \Omega(\theta) \otimes \Sigma); \theta \in \Gamma_1\} \tag{3}$$

$$E_2 = \{g_{r \times k}(\mathbf{y}; \Lambda, \Omega(\xi) \otimes \Sigma); \xi \in \Gamma_2\}. \tag{4}$$

Next visualize the ensemble E_1 to have mixing parameters θ , and E_2 to have mixing parameters ξ . Then mixtures in $\mathbb{F}_{r \times k}$ of type

$$f_i(\mathbf{y}; \Lambda, G_i) = \int_{\Gamma_i} g_{r \times k}(\mathbf{y}; \Lambda, \Omega(i) \otimes \Sigma) dG_i(\cdot) \tag{5}$$

emerge with $G_i \in \{G_1, G_2\}$ as *cdfs* on $\Gamma_i \in \{\Gamma_1, \Gamma_2\}$, and with $\Omega(i) \in \{\Omega(\theta), \Omega(\xi)\}$. In particular, the densities $f_1(\mathbf{y}; \Lambda, G_1)$ and $f_2(\mathbf{y}; \Lambda, G_2)$ are dispersion mixtures of elliptical Gaussian distributions on $\mathbb{F}_{r \times k}$ centered at $\Lambda \in \mathbb{F}_{r \times k}$. Let \mathcal{G}_1 and \mathcal{G}_2 comprise all *cdfs* on Γ_1 and Γ_2 , respectively; these in turn generate the collections

$$M_1 = \{f_1(\mathbf{y}; \Lambda, G_1); G_1 \in \mathcal{G}_1\} \tag{6}$$

$$M_2 = \{f_2(\mathbf{y}; \Lambda, G_2); G_2 \in \mathcal{G}_2\} \tag{7}$$

comprising all dispersion mixtures of the referenced types.

3. The Principal Findings

3.1 Overview

Taking $\{Y_0 = \mathbf{1}_n \cdot \boldsymbol{\mu}' + \mathcal{E}_0\}$ in $\mathbb{F}_{r \times k}$ as in Definition 1, we rearrange elements such that $Y_0 = [Y', Y_i]'$, $\mathcal{E}_0 = [\mathcal{E}', \epsilon_i]'$, and $E_0 = [E', e_i]'$, and consider arbitrary shifts $\{Y_i \rightarrow Y_i + \delta_i\}$. Nonstandard versions of $\mathcal{L}(T_i^2)$ as in expression (1) are to be studied, but where the independence of $\{Y_1, \dots, Y_n\}$ fails. Instead take $\mathcal{L}(Y_0) = N_{r \times k}(M, \Omega \otimes \Sigma)$ with $\Omega \in \{\Omega(\rho), \Omega(\xi)\}$, equivalently $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$, as the basic model undergirding the T_i^2 diagnostics. Here $M = \Lambda = \mathbf{1}_n \cdot \boldsymbol{\mu}' + \Delta$ from Assumption A₁. It is seen that shifts $\{Y_i \rightarrow Y_i + \delta_i\}$ propagate into noncentrality parameters of $\mathcal{L}(T_i^2)$. These findings in turn rest on matrices of quadratic and bilinear forms of type $Y_0' A Y_0$ in the observed data matrix $Y_0 \in \mathbb{F}_{r \times k}$ as in Appendix A.1. Here Y_i is a generic test case; another would entail rearranging Y_0 as $Y_0 = [Y', Y_j]'$.

3.2 Properties of Residuals

The observed residuals E_0 under Assumptions A are germane, as T_i^2 is a function of these. In particular, it remains to evaluate $E(e_i)$, $\text{Var}(e_i)$ and $\mathcal{L}(e_i)$ as special cases. Details follow, where $r = (n-1)$ and $E(\mathcal{E}_0) = \Delta = [\mathbf{0}', \delta_i]'$ as Assumption A₁, and $B_n = (\mathbf{I}_n - \frac{1}{n}\mathbf{1}_n\mathbf{1}'_n)$.

Theorem 1. Consider the ordinary residuals $E_0 = [E', e_i]'$ under Assumptions A, with $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$, and let $T(E_0)$ be a mapping to a linear space \mathbb{V} . Then the following properties hold independently of $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$.

(i) $\mathbb{V}(E_0) = B_n \otimes \Sigma$ and $\mathcal{L}(E_0) = N_{r \times k}(\Delta, B_n \otimes \Sigma)$;

(ii) $E(e_i) = \frac{r}{n}\delta_i$, $\mathbb{V}(e_i) = \frac{r}{n}\Sigma$, and $\mathcal{L}(e_i) = N_k(\frac{r}{n}\delta_i, \frac{r}{n}\Sigma)$;

(iii) $\mathcal{L}(T(E_0|\Omega)) = \mathcal{L}(T(E_0|\mathbf{I}_n))$.

Proof. Observe from $E_0 = B_n Y_0$ and the conventions of Appendix A.1 that $V(E_0) = B_n \Omega B_n \otimes \Sigma = B_n \otimes \Sigma$ for $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$, since $B_n \mathbf{1}_n = \mathbf{0}$ annihilates successive terms in expansions for $\Omega(\theta)$ and $\Omega(\xi)$ in the product terms following the first. This together with Assumption A_3 gives (i). The expected product $E(E_0) = (I_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}'_n) \Delta$ in partitioned form is

$$E \begin{bmatrix} E \\ e'_i \end{bmatrix} = \frac{1}{n} \begin{bmatrix} (nI_r - \mathbf{1}_r \mathbf{1}'_r) & -\mathbf{1}_r \\ -\mathbf{1}'_r & r \end{bmatrix} \begin{bmatrix} \mathbf{0} \\ \delta'_i \end{bmatrix} = \frac{1}{n} \begin{bmatrix} -\mathbf{1}_r \delta'_i \\ r \delta'_i \end{bmatrix}. \tag{8}$$

Thus $E(e_i) = r \delta_i / n$ and $V(e_i) = \frac{r}{n} \Sigma$ is the (n, n) block of $B_n \otimes \Sigma$ which, together with normality, give conclusion (ii). Conclusion (iii) follows directly. ■

3.3 Nonstandard Matrix Forms

Generalizing from Lemma A.1(iii) of Jensen (2001a) and from Jensen and Ramirez (2014) in extending to include matrix arrays, the multivariate Fisher–Cochran expansion generating T_i^2 is

$$Y'_0 A_1 Y_0 + Y'_0 A_2 Y_0 = Y'_0 A_3 Y_0; \tag{9}$$

$$\frac{n}{r} e_i e'_i + (r-1) S_i = E'_0 E_0; \tag{10}$$

where (e_i, δ_i) are of order $(k \times 1)$, and the second line explains the first. Moreover, (A_1, A_2, A_3) are idempotent as given explicitly in Jensen and Ramirez (2015), namely, $A_3 = B_n = (I_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}'_n)$, $A_2 = \text{Diag}(B_r, \mathbf{0})$ with $B_r = (I_r - \frac{1}{r} \mathbf{1}_r \mathbf{1}'_r)$, and $A_1 = A_3 - A_2$. To continue, designate the aforementioned matrix forms as $Q_1 = Y'_0 A_1 Y_0$, $Q_2 = Y'_0 A_2 Y_0$, and $Q_3 = Y'_0 A_3 Y_0$, and recall that $M = \Lambda = \mathbf{1}_n \cdot \mu' + \Delta$.

Theorem 2. Given $\mathcal{L}(Y_0) = N_{n \times k}(\Lambda, \Omega \otimes \Sigma)$ under Assumptions A; take $E_0 = B_n Y_0$; and consider the matrix forms $\{Q_1, Q_2, Q_3\}$ as in (9). Then despite dependencies among elements of $Y_0 = [Y_1, \dots, Y_n]'$ we have for each $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$ the following.

- (i) $\mathcal{L}(Q_1) = W_k(1; \Sigma, \Theta_i)$, $\Theta_i = \frac{r}{n} \delta_i \delta'_i$;
- (ii) $\mathcal{L}(Q_2) = W_k(r-1; \Sigma, \mathbf{0})$;
- (iii) $\mathcal{L}(Q_3) = W_k(r; \Sigma, \Theta_i)$;
- (iv) Q_1 and Q_2 are distributed independently;
- (v) $T_i^2 = (r-1) \text{tr } Q_1 Q_2^{-1}$;
- (vi) $\{\mathcal{L}(T_i^2) = T_k^2(u; r-1, \lambda_i); \lambda_i = \frac{r}{n} \delta'_i \Sigma^{-1} \delta_i; 1 \leq i \leq n\}$.

Proof. Fix $u \in \mathbb{R}^k$ and let $\{Q_i^u = u' Y'_0 A_i Y_0 u; i = 1, 2, 3\}$, such that $\mathcal{L}(u' Y_0) = N_n(u' \Lambda, \sigma_u^2 \Omega)$ with $\sigma_u^2 = u' \Sigma u$. Drawing on Mathai and Provost (1992, page 201), Jensen and Ramirez (2015) established conclusions (i)–(iv) for (Q_1^u, Q_2^u, Q_3^u) in terms of the corresponding χ^2 distributions on demonstrating that $\{A_i \Omega A_i = A_i; i = 1, 2, 3\}$ and that $A_1 \Omega A_2 = \mathbf{0}$ for $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$, as in Appendix A.1 of Jensen and Ramirez (2015). Theorem A.1 of the attached Appendix now lifts those results to encompass the Wishart distributions of conclusions (i)–(iv). Conclusion (v) follows directly from expressions (1) and (10), and conclusion (vi) as the Wishart analog of the noncentral properties of Theorem A.1 of Jensen and Ramirez (2015). ■

3.4 Invariance under Mixtures

That the T_i^2 diagnostics may be valid under star–contoured errors is the subject of the following, where $\Lambda = \mathbf{1}_n \cdot \mu' + \Delta$ as in Assumption A_1 .

Theorem 3. Given the model $\{Y_0 = \Lambda + \mathcal{E}_0\}$ having a Gaussian mixture density $f_1(y_0; \Lambda, G_1)$ in M_1 or $f_2(y_0; \Lambda, G_2)$ in M_2 as in Section 2.4.

- (i) Tests using T_i^2 remain exact in level and power for all mixtures in M_1 ;
- (ii) Tests using T_i^2 remain exact in level and power for all mixtures in M_2 ;
- (iii) These T_i^2 distributions are identical to those derived from $\mathcal{L}(Y_0) = N_{n \times k}(\Lambda, I_n \otimes \Sigma)$.

Proof. Return to Section 2.4 and expression (5). We argue conditionally as follows: (i) Fix $\Omega \in \{\Omega(\theta), \Omega(\xi)\}$; (ii) note from Theorem 3.2(vi) that $\mathcal{L}(T_i^2)$ holds independently of Ω ; then (iii) make the change–of–variables behind the integral,

to conclude for $\{i = 1, 2\}$ that

$$f_i(\mathbf{y}_0, \mathbf{\Lambda}, G_i) = \int_{\Gamma_i} g_{r \times k}(\mathbf{y}_0; \mathbf{\Lambda}, \mathbf{\Omega} \otimes \mathbf{\Sigma}) dG_i(\cdot)$$

$$f_i(\mathbf{y}_0, \mathbf{\Lambda}, G_i) \rightarrow \int_{\Gamma_i} T_k^2(u; r-1, \lambda_i) dG_i(\cdot) = T_k^2(u; r-1, \lambda_i)$$

independently of $\mathbf{\Omega} \in \{\mathbf{\Omega}(\theta), \mathbf{\Omega}(\xi)\}$ and of G_i , and since $\int_{\Gamma_i} dG_i = 1$. ■

3.5 Left-Spherical Matrix Distributions

Other structured distributions are germane. This section draws heavily from Jensen and Good (1981).

Definition 2. A distribution on $\mathbb{F}_{r \times k}$ is *left-spherical* provided that $\mathcal{L}(X) = \mathcal{L}(PX)$ for every orthogonal matrix $P \in O(n)$. Denote by $L_{r \times k}(\mathbf{0}, \mathbf{I}_n)$ the class of left-spherical matrix distributions centered at the origin in $\mathbb{F}_{r \times k}$, in which case its *chf* has the form $\phi_X = \psi(\text{tr } T'T)$ with argument $T \in \mathbb{F}_{r \times k}$.

Nor are these required to have moments of various orders: examples are the *left-spherical stable laws* on $\mathbb{F}_{r \times k}$ having *chfs* of type

$$\phi_X(T) = \exp(\gamma[\text{tr}(T'T)]^{\frac{\alpha}{2}}) \tag{11}$$

with parameters $\{\gamma < 0, 0 < \alpha < 2\}$ of which the matrix Cauchy law with $\alpha = 1$ is a noteworthy special case. In addition, the shift $\{X \rightarrow Z = X + \mathbf{M}\}$ gives $\mathcal{L}(Z) = L_{r \times k}(\mathbf{M}, \mathbf{I}_n)$.

To continue, let \mathfrak{M} be a linear subspace of $\mathbb{F}_{r \times k}$. The following is fundamental.

Definition 3. The transformation $T : \mathbb{F}_{r \times k} \rightarrow \mathcal{V}$ is said to be *translation-invariant* with respect to \mathfrak{M} if, for each $Z \in \mathbb{F}_{r \times k}$ and $\mathbf{M} \in \mathfrak{M}$, $T(Z + \mathbf{M}) = T(Z)$. In addition, T is *right-invariant* under $\mathcal{G}l(k)$ if, for every $B \in \mathcal{G}l(k)$, $T(ZB) = T(Z)$.

The following is given as Theorem 2 of Jensen and Good (1981).

Lemma 2. Suppose $\mathcal{L}(Z) \in \{L_{r \times k}(\mathbf{M}, \mathbf{I}_n); \mathbf{M} \in \mathfrak{M}\}$, and let the transformation $T : \mathbb{F}_{r \times k} \rightarrow \mathcal{V}$ be translation-invariant with respect to \mathfrak{M} and be right-invariant under $\mathcal{G}l(k)$. Then the distribution of $T(Z)$ is the same for all $\mathcal{L}(Z) \in L_{r \times k}(\mathbf{M}, \mathbf{I}_n)$ independently of \mathbf{M} , and thus is identical to its matrix normal theory form.

We next examine T_i^2 under $\mathcal{L}(Y_0) = L_{r \times k}(\mathbf{\Lambda}, \mathbf{I}_n)$, where $\mathbf{\Lambda} = \mathbf{1}_n \cdot \boldsymbol{\mu}' + [\mathbf{O}', \boldsymbol{\delta}_i]'$ with $\mathbf{O}(r \times k)$ a matrix of zeroes as in Assumption A₁. We proceed in two steps, first taking $Y_0 \rightarrow \mathbf{G}Y_0$, then the latter into T_i^2 , namely,

$$\mathbf{G}Y_0 = \begin{bmatrix} \mathbf{B}_r & \mathbf{0} \\ -\frac{1}{n}\mathbf{1}_r' & (1 - \frac{1}{n}) \end{bmatrix} \begin{bmatrix} \mathbf{Y} \\ \mathbf{Y}' \end{bmatrix} = \begin{bmatrix} \mathbf{B}_r \mathbf{Y} \\ \mathbf{e}' \end{bmatrix} \rightarrow \frac{n}{r} \mathbf{e}'_i [\mathbf{Y}' \mathbf{B}_r \mathbf{Y}]^{-1} \mathbf{e}_i = T_i^2. \tag{12}$$

As $\mathbf{B}_r \mathbf{Y}$ contains deviations from means, it is clear that $(n-1)S_i = \mathbf{Y}' \mathbf{B}_r \mathbf{Y}$. In addition, the final row of \mathbf{G} is $\mathbf{u}' = [-\frac{1}{n}, \dots, -\frac{1}{n}, (1 - \frac{1}{n})]$, so that $\mathbf{u}' \mathbf{Y}_0 = \mathbf{e}'_i$. Moreover, under Assumptions A, $E(\mathbf{B}_r \mathbf{Y}) = \mathbf{O}$ and $E(\mathbf{e}_i) = \boldsymbol{\delta}_i$.

To continue, let $\mathfrak{M} = \{\mathbf{1}_n \cdot \boldsymbol{\mu}' \mid \boldsymbol{\mu} \in \mathbb{R}^k\}$. We have the following.

Theorem 4. Suppose that $\mathcal{L}(Y_0) \in \{L_{r \times k}(\mathbf{M}, \mathbf{I}_n); \mathbf{M} \in \mathfrak{M}\}$, and consider testing $H_0 : \boldsymbol{\delta}_i = \mathbf{0}$ against $H_1 : \boldsymbol{\delta}_i \neq \mathbf{0}$.

(i) Then the null distribution of T_i^2 is the same for all $\mathcal{L}(Y_0) \in \{L_{r \times k}(\mathbf{M}, \mathbf{I}_n); \mathbf{M} \in \mathfrak{M}\}$ and thus is identical to its matrix normal theory form.

(ii) This holds in particular for every left-spherical stable law on $\mathbb{F}_{r \times k}$ having moments of order up to but excluding α .

Proof. Conclusion (i) follows directly from Lemma 2, where the translation invariance of T_i^2 , and its right-invariance under $\mathcal{G}l(k)$, are readily apparent. Observe that developments including the definition of \mathfrak{M} are devoid of $\boldsymbol{\delta}_i$, i.e. $\boldsymbol{\delta}_i = \mathbf{0}$, so that Lemma 2 establishes invariance of the null distribution $\mathcal{L}(T_i^2 | H_0)$. Conclusion (ii) follows on recognizing that moments are not required in the developments of earlier sections. Specifically, $\mathbf{\Lambda} = \mathbf{1}_n \cdot \boldsymbol{\mu}' + [\mathbf{O}', \boldsymbol{\delta}_i]'$ of Assumptions A may be taken to be location and shift parameters without first moments, and the earlier dispersion parameters $\mathbf{I}_n \otimes \mathbf{\Sigma}$ serve instead as scale parameters of the distributions *in lieu of* second moments. ■

Remark 1. It is nothing short of remarkable that operating characteristics of T_i^2 should be identical under matrix Cauchy errors as under matrix Gaussian errors. The importance of heavy-tailed distributions in economics and finance is highlighted in Ibragimov *et al.* (2015) as noted.

4. Case Studies

4.1 Overview

Calibrated data often entail *calibration curves*, direct or indirect, both injecting dependencies among the calibrated measurements; see Jensen and Ramirez (2009, 2012). These apply in the analysis of univariate data. Another venue adjusts observations directly to a common standard, as in compensating for the *tare weight* of a scale, or in assessing yield increments relative to a control yield as in Jensen (2001b). Subsequent examples fall within the latter framework, which we develop next for multivariate data amenable to Hotelling’s T_i^2 diagnostics.

In short, observations $Y_0 = [Y_1, \dots, Y_n]'$ from $\{Y_0 = \mathbf{1}_n \mu' + \mathcal{E}_0\}$ are sought. For Case I the user sees $Z_0 = [Z_1, \dots, Z_n]'$ having $\{Z_j = Y_j + \mathbf{W} \in \mathbb{R}^k; 1 \leq j \leq n\}$ with scalar shifts $\mathbf{W} = [W_1, \dots, W_k]$ often themselves random. To model this we proceed as follows: (a) Append $Y_0^\dagger = [Y_1, \dots, Y_n, \mathbf{W}]'$; (b) suppose that $V(Y_0^\dagger) = I_N \otimes \Sigma$ with $N = n + 1$; and (c) let $A = [I_n, \mathbf{1}_n]$. Then $Z_0 = AY_0^\dagger \in \mathbb{F}_{n \times k}$. For Case II, if rows of Y_0 are to be adjusted instead against \mathbf{W} as standard, then $\{Z_j = (Y_j - \mathbf{W}); 1 \leq j \leq n\}$ and $A = [I_n, -\mathbf{1}_n]$. To continue, in both cases we have $V(Z_0) = AI_N A' \otimes \Sigma$ from Remark A.1. In what follows we parallel steps given heretofore in working from Y_0 to T_i^2 .

Lemma 3. *Begin with Z_0 as constructed; rearrange as $Z_0 = [Z', Z_i]'$ with Z_i as the test case; and determine T_i^2 from Z_0 as before using Y_0 . Then*

- (i) *The residuals $R_0 = B_n Z_0$ have $V(R_0) = B_n \otimes \Sigma$ independently of \mathbf{W} ;*
- (ii) *$\mathcal{L}(T_i^2) = T_k^2(u; r - 1, \lambda_i)$ independently of \mathbf{W} , with $\lambda_i = \frac{r}{n} \delta_i' \Sigma^{-1} \delta_i$;*
- (iii) *T_i^2 remains exact in level and power for all mixtures in M_1 of (5);*
- (iv) *These T^2 distributions are identical to those initially derived from the unadjusted $\mathcal{L}(Y_0) = N_{n \times k}(\mathbf{A}, I_n \otimes \Sigma)$.*

Proof. Taking $V(Z_0) = AA' \otimes \Sigma$ from $A = [I_n, \pm \mathbf{1}_n]$, it follows that $B_n AA' B_n \otimes \Sigma = B_n \otimes \Sigma$ since B_n is idempotent, to give conclusion (i). Conclusion (ii) follows directly, setting the stage so that conclusions (iii)–(iv) now follow from Theorem 3, to complete our proof. ■

Remark 2. Observe that a fractional adjustment $\{Z_j = (Y_j \pm \kappa \mathbf{W}); 1 \leq j \leq n\}$ can be achieved on taking $A = [I_n, \pm \kappa \mathbf{1}_n]$. The stated conclusions follow directly if so modified.

4.2 Simulation Studies

As developments heretofore are tedious, convoluted, and unconventional, it is instructive to demonstrate Theorem 2 and then Theorem 3. Details follow.

(i) Induced Correlations.

Accordingly, $N = 40,000$ random samples $Y_0 \in \mathbb{F}_{n \times k}$ of size $n = 10$ and $k = 2$ were generated from $N_{n \times k}(\mathbf{0}, I_n \otimes \Sigma)$ with rows as independent bivariate Gaussian vectors having zero means and dispersion matrix $\Sigma = \begin{bmatrix} 1.0 & 0.8 \\ 0.8 & 1.0 \end{bmatrix}$. Correlations among rows were induced through $Y_0 \rightarrow Z_0 = [\Omega(\theta)]^{\frac{1}{2}} Y_0$ using the spectral square root, so that $V(Z_0) = \Omega(\theta) \otimes \Sigma$ using Remark A.1. In consequence, rows of Z_0 are equicorrelated with $\rho = \theta / (1 + \theta)$ and, to illustrate, we vary $\rho \in [0.0, 0.2, 0.5, 0.8]$ with corresponding $\theta \in [0.00, 0.25, 1.00, 4.00]$. MINITAB was used for all the simulations.

Table 1 reports the empirical critical values for T_i^2 corresponding to tabulated critical values c_α from Theorem 2(vi) such that $\mathcal{L}(T_i^2) = T_k^2(u; r - 1, 0)$. The row being evaluated for a potential shift is set to $i = 10$. Computations yielding T_i^2 were undertaken for each repetition, with results as summarized in Table 1.

Table 1. Tabulated and empirical critical values for $\{T_i^2 \geq c_\alpha\}$, $N = 40,000$ runs, for correlated Z_0 with varying ρ such that $V(Z_0) = \Omega(\theta) \otimes \Sigma$ with $\theta = \rho / (1 - \rho)$, $n = 10$, and $k = 2$.

α	10%	5%	2.5%	1%
Tabulated c_α	7.45	10.83	14.95	21.82
$\rho = 0.0$	7.40	10.77	14.65	21.84
$\rho = 0.2$	7.40	10.77	14.65	21.84
$\rho = 0.5$	7.40	10.77	14.65	21.84
$\rho = 0.8$	7.40	10.77	14.65	21.84

Table 2. Tabulated and empirical powers for $\{T_i^2 \geq c_\alpha\}$, $N=40,000$, with varying shifts $\delta' = [\delta_1, \delta_2]$ for correlated Z_0 such that $V(Z_0) = \Omega(\theta) \otimes \Sigma$ with $\theta=1$, $n=10$, and $\lambda_i = \frac{r}{n} \delta_i' \Sigma^{-1} \delta_i$.

δ_1	δ_2	k	$r-k$	λ_i	Tabulated Power	Empirical Power
0	0	2	7	0.000	0.0500	0.0496
1	1	2	7	1.000	0.1020	0.1036
2	2	2	7	4.000	0.2848	0.2822
3	3	2	7	9.000	0.5670	0.5647
4	4	2	7	16.000	0.8188	0.8177
5	5	2	7	25.000	0.9504	0.9499

Table 2 reports the empirical power for T_i^2 with noncentrality parameter $\lambda_i = \frac{r}{n} \delta_i' \Sigma^{-1} \delta_i$ as in Theorem 2(vi). The corresponding tabulated power as in Theorem 2(vi) is from $\mathcal{L}(T_i^2) = T_k^2(u; r-1, \lambda_i)$, where the shifts were added to the residual for row $i=10$. Table 2 demonstrates that the powers for Hotelling's T_i^2 diagnostics under equicorrelated data are equivalent to those tabulated for independent data. Recalling that $\mathcal{L}(\frac{r-k}{k(r-1)} T_i^2) = F(u; k, r-k, \lambda_i)$, the noncentral F probabilities were computed using the Keisan Online Calculator provided by the Casio Computer Co., Ltd.

(ii) Mixture Experiments.

To demonstrate the validity of T_i^2 in mixture distributions as in Theorem 3, $N=40,000$ random samples $Y_0 \in \mathbb{F}_{n \times k}$ of size $n=10$ and $k=2$ were generated from $N_{n \times k}(\mathbf{0}, I_n \otimes \Sigma)$ having zero means and dispersion matrix $\Sigma = \begin{bmatrix} 1.0 & 0.8 \\ 0.8 & 1.0 \end{bmatrix}$. As before, correlations among the rows were induced through $Y_0 \rightarrow Z_1 = [\Omega(\theta_1)]^{\frac{1}{2}} Y_0$ so that $V(Z_1) = \Omega(\theta_1) \otimes \Sigma$ using Remark A.1. This was repeated with $Y_0 \rightarrow Z_2 = [\Omega(\theta_2)]^{\frac{1}{2}} Y_0$ to form another correlated data set.

For a 50%-50% mixture, $m=5$ observations were randomly chosen from each of Z_1 and Z_2 and stacked in random order to form a data set of order (10×2) . Table 3 reports the empirical critical values for T_i^2 from Theorem 2(v), with the corresponding tabulated critical values c_α from Theorem 2(vi) where $\mathcal{L}(T_i^2) = T_k^2(u; r-1, 0)$. Values $\rho \in [0.0, 0.2, 0.5]$ were used with $\theta = \rho/(1-\rho)$. The row being evaluated for a potential shift was set to be $i=10$.

Table 3. Tabulated and empirical critical values for $\{T_i^2 \geq c_\alpha\}$, $N=40,000$, with varying ρ , for 50%-50% mixtures with correlated Z_1 having $V(Z_1) = \Omega(\theta_1) \otimes \Sigma$, and with Z_2 having $V(Z_2) = \Omega(\theta_2) \otimes \Sigma$, where $\theta = \rho/(1-\rho)$, $m=5$, $k=2$, and $n=10$.

$\Omega(\theta_1)$	$\Omega(\theta_2)$	10%	5%	2.5%	1%
$\rho_1=0.0$	$\rho_2=0.0$	7.40	10.77	14.65	21.84
$\rho_1=0.0$	$\rho_2=0.2$	7.50	10.83	15.07	21.90
$\rho_1=0.0$	$\rho_2=0.5$	7.31	10.51	14.55	21.41
$\rho_1=0.2$	$\rho_2=0.5$	7.21	10.29	14.27	20.90
Tabulated c_α		7.45	10.83	14.95	21.82

Table 3 demonstrates empirically the invariance of T_i^2 in mixture experiments. Observe that the second and third cases comprise contamination of $I_n \otimes \Sigma$, the classical model, with 50% contamination using $\Omega(\theta) \otimes \Sigma$.

4.3 Running Times Example

Woodward (1970) studied the running times for $n=22$ baseball players who ran three different paths rounding first base. These data, as used by Morrison (2005) to test for outliers, are reported in Appendix Table 7. The times that appear to be abnormal are those for Player 14 and Player 22. Using T_i^2 we see in Table 4 that the running times for Player 22 are indeed outlying with p -value 0.0138. Times for Player 14 are not flagged as outliers. However, the last four rows of Table 4 give T_i^2 for Player 14 assuming improvements in his running times in units of $\delta \in [0.1, 0.2, 0.3, 0.4]$.

Beckett (1977) has identified that the $n=22$ data points consist of two clusters, namely [2, 4, 5, 7-15, 17, 19-22] and [1, 3, 6, 16, 18], where each cluster consists of correlated data. Observe that the rank order of the times $[Y_1, Y_2, Y_3]$ for Players 1, 6, and 18 differ from the rank order for other players. In consequence, Morrison's (2005) search for outliers using T_i^2 is in dispute when based on the validating model of the day, namely $V(Y) = I_n \otimes \Sigma$, instead of the apparent mixing over clusters.

A fortunate conclusion from Theorems 2 and 3 is that searches for outliers using T_i^2 now has been validated for data sets from cohorts which are equicorrelated. And, in addition, even for data sets arising as mixture distributions, in a belated

Table 4. Values of T_i^2 for Player 22 and Player 14 with varying improvements $\delta' = [\delta_1, \delta_2, \delta_3]$ for Player 14.

Player	$\delta = [\delta_1, \delta_2, \delta_3]'$	T_i^2	n	k	$r - 1$	p -value
22		15.589	22	3	20	0.0138
14		4.886	22	3	20	0.2572
14	(-0.1, -0.1, -0.1)	6.835	22	3	20	0.1432
14	(-0.2, -0.2, -0.2)	9.094	22	3	20	0.0744
14	(-0.3, -0.3, -0.3)	11.694	22	3	20	0.0367
14	(-0.4, -0.4, -0.4)	14.624	22	3	20	0.0175

verification of Morrison’s (2005) analysis.

4.4 Adjusting to a Common Standard

Following the notation of Section 4.1, we consider a Case II example in which the data $Y_0 = [Y_1, \dots, Y_n]'$ are adjusted against a standard $\mathbf{W} = [\bar{W}_1, \dots, \bar{W}_k]$. Here $N = 40,000$ random samples $Y_0 \in \mathbb{F}_{n \times k}$ were generated from $N_{n \times k}(\mathbf{0}, I_n \otimes \Sigma(\rho))$ of size

Table 5. Tabulated and empirical critical values for $\{T_i^2 \geq c_\alpha\}$, $N = 40,000$ runs, for correlated $\{Z_j = Y_j - \mathbf{W}\}$ as Y_j adjusted to the standard \mathbf{W} , with $V(Z_0) = \Omega(\theta) \otimes \Sigma$ and $\theta = 1.0, \rho = 0.5, n = 20$ and $k = 4$.

α	10%	5%	2.5%	1%
Tabulated c_α	11.33	14.67	18.26	23.49
Empirical $c_\alpha, \rho = 0.5$	11.32	14.70	18.24	23.38

$n = 20$ and $k = 4$ with rows as independent Gaussian vectors having zero means and dispersion matrix $\Sigma(\rho) = (1 - \rho)I_4 + \rho \mathbf{1}_4 \mathbf{1}_4'$ with $\rho = 0.8$. The standardizing vector \mathbf{W} was random from $N_k(\mathbf{0}, \Sigma)$, with $\{Z_j = Y_j - \mathbf{W}; 1 \leq j \leq n\}$ and with $Z_0 = \mathbf{A}Y_0^\dagger$ as equicorrelated data with $V(Z_0) = \Omega(\theta) \otimes \Sigma$, $\theta = 1.0$ and corresponding $\rho = \theta / (1 + \theta) = 0.5$. Lemma 3(iii) notes that $T_i^2 = (r - 1)\text{tr}(\mathbf{Q}_1 \mathbf{Q}_2^{-1})$ remains exact in level and power for the equicorrelated data. Table 5 reports the tabulated and empirical critical values for this study, affirming that the critical values remain the same for data equicorrelated by adjustment to a common standard.

Table 6. Tabulated and empirical powers for $\{T_i^2 \geq c_{0.05}\}$, $N = 40,000$ runs, with varying shifts $\delta' = [\delta_i, \delta_i, \delta_i, \delta_i]$ for correlated $\{Z_j = Y_j - \mathbf{W}\}$ as Y_j adjusted to the standard \mathbf{W} , with $V(Z_0) = \Omega(\theta) \otimes \Sigma$ and $\theta = 1.0, \rho = 0.5, n = 20$ and $k = 4$, and $\lambda_i = \frac{r}{n} \delta_i' \Sigma^{-1} \delta_i$.

δ_i	k	$r - k$	λ_i	Tabulated Power	Empirical Power
0	4	15	0.000	0.0500	0.0503
1	4	15	1.118	0.0956	0.0933
2	4	15	4.471	0.2683	0.2681
3	4	15	10.059	0.5673	0.5694
4	4	15	17.882	0.8391	0.8388
5	4	15	27.941	0.9661	0.9661

Table 6 reports the tabulated and empirical powers for $\{T_i^2 \geq c_\alpha\}$ with $c_{0.05} = 14.67$ and with non-centrality parameter $\lambda_i = \frac{r}{n} \delta_i' \Sigma^{-1} \delta_i$. The shifts $\delta_i' = [\delta_1, \dots, \delta_4]$ used a common value δ_i and were added to the residuals for row $i = 20$.

5. Conclusions

The objectives set forth in the Introduction now have been met, namely, the construction of dispersion mixtures of matrix distributions under direct products of the type $V(Y_0) = \Omega \otimes \Sigma$, together with the invariance of null and nonnull distributions of T_i^2 under such mixtures. Additional findings establish the null distribution of T_i^2 to be invariant under left-spherical symmetry, encompassing matrix stable and Cauchy distributions as special cases. These findings do expand considerably the theoretical bases validating the use of T_i^2 in practice.

To place this study in perspective, users long have recognized that classical Gaussian models often are inadequate under the exigencies of contemporary research. Early remedial efforts focused on spherical and elliptical symmetries in \mathbb{R}^n , generating many well known research papers and monographs. More recent studies examine additional structural properties

in \mathbb{R}^n ; examples include Arnold *et al.* (2008), Kamiya *et al.* (2008), Sarabia and Gómez-Déniz (2008), Richter (2013), and Richter (2014). These include mixtures, asymmetries, and various star-contoured densities in \mathbb{R}^n . Among the latter are the dispersion mixtures of Jensen and Ramirez (2015), having the remarkable feature that the distributions of t_i^2 and those of Dixon (1950), Grubbs (1950), and Ferguson (1961) are all invariant and thus identical to their normal theory forms.

The present study breaks new ground in extending the n -dimensional mixture distributions of Jensen and Ramirez (2015) to include star-contoured matrix distributions in \mathbb{F}_{nk} , together with invariance of the distribution of T_i^2 . The case studies offer further insight regarding the extended uses of T_i^2 in practice.

A Appendix

A.1 Matrix Distributions

We collect basics for matrix distributions essential to the present study. First partition Y_0 by columns as $Y_0 = [Y_1, \dots, Y_k] \in \mathbb{F}_{nk}$. Alternatively, if instead we row-partition as $Y_0' = [Z_1, \dots, Z_n]$, then we adopt the convention that $V(Y_0) = \Omega \otimes \Sigma$, so that $\{V(Z_i) = \omega_{ii}\Sigma, 1 \leq i \leq n\}$. Moreover, if $V(Y) = \Omega \otimes \Sigma$ of order $(nk \times nk)$, then for fixed (A, B) and for $U = AYB'$, the corresponding moment arrays are as follow.

Remark 3. $E(Z) = AMB'$ and $V(Z) = A\Omega A' \otimes B\Sigma B'$.

(i) Gaussian Distributions

Designate the distribution of $Y \in \mathbb{F}_{nk}$ as $\mathcal{L}(Y) = N_{nk}(M, \Omega \otimes \Sigma)$, the *matrix Gaussian* distribution in \mathbb{F}_{nk} having $E(Y) = M$ and $V(Y) = \Omega \otimes \Sigma$. Its *pdf* is

$$f_{nk}(Y) = (2\pi)^{-\frac{nk}{2}} |\Omega|^{-\frac{k}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left[-\frac{1}{2} \text{tr} \Omega^{-1}(Y - M)\Sigma^{-1}(Y - M)' \right]. \tag{13}$$

Next partition $Y = [Y_1, Y_2]$, $M = [M_1, M_2]$, and $\Sigma = [\Sigma_{ij}; i, j = 1, 2]$. Here (Y_1, M_1) are of order $(n \times r)$; (Y_2, M_2) are of order $(n \times s)$; and elements of Σ are $\{\Sigma_{11}(r \times r), \sigma_{12}(r \times s), \sigma_{21}(s \times r), \sigma_{22}(s \times s)\}$. Then

- Marginals: $\mathcal{L}(Y_1) = N_{nr}(M_1, \Omega \otimes \Sigma_{11})$; $\mathcal{L}(Y_2) = N_{ns}(M_2, \Omega \otimes \sigma_{22})$.
- Conditional: $\mathcal{L}(Y_1|Y_2 = y_2) = N_{nr}(M_{1.2}, \Omega \otimes \Sigma_{11.2})$ with $M_{1.2} = M_1 + (y_2 - M_2)R'$ and $R = \sigma_{12}\sigma_{22}^{-1}$.

(ii) Wishart Distributions

Take $\mathcal{L}(Y) = N_{nk}(M, I_n \otimes \Sigma)$; let $W = Y'Y$; and partition $W = [W_{ij}; i, j = 1, 2]$ and $\Sigma = [\Sigma_{ij}; i, j = 1, 2]$ conformably. Here elements of W are $\{W_{11}(r \times r), W_{12}(r \times s), W_{21}(s \times r), W_{22}(s \times s)\}$. Define $W_{11.2} = W_{11} - W_{12}W_{22}^{-1}W_{21}$, and $\Sigma_{11.2}$ as before.

- W is said to have the Wishart distribution $\mathcal{L}(W) = \mathbb{W}_k(n; \Sigma, \Theta)$ with n degrees of freedom, the scale parameters Σ , and the noncentrality matrix $\Theta = M'M$.
- Marginals: $\mathcal{L}(W_{11}) = \mathbb{W}(n; \Sigma_{11}, M_1'M_1)$ and $\mathcal{L}(W_{22}) = \mathbb{W}_s(n, \sigma_{22}, M_2'M_2)$.
- Conditional: $\mathcal{L}(W_{11.2}|Y_2 = y_2) = \mathbb{W}(n - s; \Sigma_{11.2}, \Theta(y_2))$ with $\Theta(y_2) = M_{1.2}'M_{1.2}$ and $M_{1.2} = M_1 + R(y_2 - M_2)$ with $R = \sigma_{12}\sigma_{22}^{-1}$.
- A standard result is that if A is idempotent of rank ν , and if $W = Y'AY$, then $\mathcal{L}(W) = \mathbb{W}_k(\nu, \Sigma, \Theta)$ with $\Theta = M'AM$.

(iii) A characterization

Fundamental connections link noncentral chi-squared and noncentral Wishart distributions. To wit: The noncentral Chi-squared and Wishart *chf*'s are

$$\begin{aligned} \phi_Z(t) &= (1 - 2it\sigma^2)^{-\frac{n}{2}} \exp[it \theta^2 / (1 - 2it\sigma^2)] \\ \phi_W(T) &= |I_k - 2iT\Sigma|^{-\frac{n}{2}} \exp[i \text{tr} T\Theta(I_k - 2iT\Sigma)^{-1}], \end{aligned}$$

respectively. The following is germane.

Theorem 5. Let $\mathcal{L}(Y) = N_{nk}(M, I_n \otimes \Sigma)$, and take $W = Y'AY$ such that A is idempotent of rank ν .

(i) If $\mathcal{L}(W) = \mathbb{W}_k(\nu, \Sigma, \Theta)$, then $\mathcal{L}(u'Wu) = \chi^2(\nu, \sigma_u^2, \lambda(u))$ for every $u \in \mathbb{R}^k$, where $\sigma_u^2 = u'\Sigma u$ and $\lambda(u) = u'\Theta u$.

(ii) Conversely, if $\mathcal{L}(\mathbf{u}'\mathbf{W}\mathbf{u}) = \chi^2(\nu, \sigma_{\mathbf{u}}^2, \lambda(\mathbf{u}))$ for every $\mathbf{u} \in \mathbb{R}^k$, then $\mathcal{L}(\mathbf{W}) = \mathbb{W}_k(\nu, \boldsymbol{\Sigma}, \boldsymbol{\Theta})$.

(iii) Define $\mathbf{W}_1 = \mathbf{Y}'\mathbf{A}_1\mathbf{Y}$ and $\mathbf{W}_2 = \mathbf{Y}'\mathbf{A}_2\mathbf{Y}$ with $\mathbf{A}_1 \neq \mathbf{A}_2$. Then $(\mathbf{W}_1, \mathbf{W}_2)$ are mutually independent Wishart matrices if and only $(\mathbf{u}'\mathbf{W}_1\mathbf{u}, \mathbf{u}'\mathbf{W}_2\mathbf{u})$ are mutually independent χ^2 variates for every $\mathbf{u} \in \mathbb{R}^k$.

Proof. Conclusion (i) follows on substituting $t\mathbf{u}\mathbf{u}'$ for \mathbf{T} in the *chf* for \mathbf{W} , together with the fact that the nonvanishing eigenvalue of $\mathbf{u}\mathbf{u}'$ is $\mathbf{u}'\mathbf{u}$. Conclusion (ii) follows on lifting from \mathbb{R}_+^1 to \mathbb{S}_k^+ ; this may be done using the characterization of Cramér and Wold (1936), as carried out in Jensen (1982). Conclusion (iii) follows from (i) and (ii) on verifying that the joint *chf*'s of $(\mathbf{W}_1, \mathbf{W}_2)$ and of $(\mathbf{u}'\mathbf{W}_1\mathbf{u}, \mathbf{u}'\mathbf{W}_2\mathbf{u})$ factor into the product of their marginal *chf*'s. ■

Remark 4. The central version of conclusions (i) and (ii) was given in Result (ii) of Rao (1973, page 535).

A.2 Running Times Data

The data employed in Section 4.3 are listed here as reported in Morrison (2005, page 102).

Table 7. Running times around first base for $k=3$ paths and $n=22$ players.

Player	Y ₁	Y ₂	Y ₃	Player	Y ₁	Y ₂	Y ₃
1	5.40	5.50	5.55	12	5.65	5.55	5.45
2	5.85	5.70	5.75	13	5.60	5.35	5.45
3	5.20	5.60	5.50	14	5.05	5.00	4.95
4	5.55	5.50	5.40	15	5.50	5.50	5.40
5	5.90	5.85	5.70	16	5.45	5.55	5.50
6	5.45	5.55	5.60	17	5.55	5.55	5.35
7	5.40	5.40	5.35	18	5.45	5.50	5.55
8	5.45	5.50	5.35	19	5.50	5.45	5.25
9	5.25	5.05	5.00	20	5.65	5.60	5.40
10	5.85	5.80	5.70	21	5.70	5.65	5.55
11	5.25	5.20	5.10	22	6.30	6.30	6.25

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