# A Parametric Test to Discriminate Between a Linear Regression Model and a Linear Latent Growth Model 

Marco Barnabani ${ }^{1}$<br>${ }^{1}$ Department of Statistics, Informatics, Applications, V.le Morgagni, 59, 50134 Florence, Italy<br>Correspondence: Marco Barnabani, Department of Statistics, Informatics, Applications, V. le Morgagni, 59, 50134 Florence, Italy. E-mail: barnaban@disia.unifi.it

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#### Abstract

In longitudinal studies with subjects measured repeatedly across time, an important problem is how to select a model generating data by choosing between a linear regression model and a linear latent growth model. Approaches based both on information criteria and asymptotic hypothesis tests of the variances of "random" components are widely used but not completely satisfactory. We propose a test statistic based on the trace of the product of an estimate of a variance covariance matrix defined when data come from a linear regression model and a sample variance covariance matrix. We studied the sampling distribution of the test statistic giving a representation in terms of an infinite series of generalized $F$-distributions. Knowledge about this distribution allows us to make inference within a classical hypothesis testing framework. The test statistic can be used by itself to discriminate between the two models and/or, if duly modified, it can be used to test randomness on single components. Moreover, in conjunction with some model selection criteria, it gives additional information which can help in choosing the model.


Keywords: Generalized $F$-distribution, Hypothesis testing, Linear Mixed Models

## 1. Introduction

It is common practice in many applications to collect multiple measurements on subjects across time by focusing on the process of change when, typically, both data dependency and differential growth for different individuals can occur. If we assume that the subjects constitute a sample from the population of interest and we wish to draw conclusions about typical patterns in the population and the subject-to-subject variability of these patterns, we are fitting linear latent growth models. In this paper these models are analyzed by using a mixed-modeling framework (Laird \& Ware, 1982). Linear mixed models can be viewed as extensions of linear regression models and attempt to account for within-subject dependency in the multiple measurements by including one or more subject-specific latent variables in the regression model. Typically, an additional random effect is included for each regression coefficient that is expected to vary among subjects. An important practical problem is how to discriminate between a linear regression model and a linear mixed model and how to choose the random effect components. In order to address the issue of which model is more suitable, one might use standard model selection measures based on information criteria such as the widely used Akaike Information Criteria (AIC; Akaike, 1973), the Bayesian Information Criteria (BIC; Schwarz, 1978) the conditional Akaike Information Criterion (cAIC, Vaida \& Blanchard, 2005). These approaches are based on the choice of models that minimize an estimate of a specific criterion which usually involves a trade-off between the closeness of the fit to the data and the complexity of the model. We refer to the paper of Muller et al. (2013) for a review of these approaches and other methods such as shrinkage methods like the LASSO (Tibshirani, 1996), Fence methods (Jiang et al., 2008) and Bayesian methods. The validity of all the methods proposed depends on the underlying assumptions. The review paper of Muller et al. (2013) gives an overview of the limits and most important findings of above approaches, extracting information from some published simulation results. As is known, one of the major drawbacks of these approaches is that they fail to give any measure of the degree of uncertainty of the model chosen. The value they produce has not a straight-forward interpretation.
Alternatively, because model selection is closely related to hypothesis testing, the choice between a linear regression model ( $L R M$ ) and a linear latent growth model ( $L L G M$ ) and the evaluation of its uncertainty could be conducted considering a formal hypothesis test on the variances of "random" components. Noting that models are nested, it is natural to consider the likelihood ratio test. However, the difficulty with this is that it makes the usual approach of comparing the likelihood ratio test statistic with the chi-square distribution inappropriate. The question of whether the variance of a component is zero depends on whether said variance takes its value on the boundary of the parameter space. This situation is known as "non-standard" in relation to the other uses of the likelihood ratio test. The major consequence is that in large samples -2 times the logarithm of the likelihood ratio cannot be treated as a chi-square distribution, but rather, as a mixture of chi-square distributions. Determining the weights of this mixture distribution is difficult especially for testing multiple variance components or a subset of them. For more details see, for example, Self \& Lang (1987), Stram \& Lee (1994),

Verbeke \& Molenberghs (2003), Giampaoli \& Singer 2009. Comparing the likelihood ratio statistic with the critical value from a chi-square sampling distribution tends not to reject the null as often as it should. Other tests not based on the likelihood function can be implemented Silvapulle \& Sen (2005) but their validity should be carefully detected when applied to linear mixed models. Moreover, all these tests are only valid asymptotically. Finite sample distributions of the likelihood ratio test require simulations and are only reported in particular cases. For example, Crainiceanu \& Ruppert 2004 introduced an efficient simulation algorithm based on the spectral representations of the likelihood ratio test and the restricted likelihood ratio test statistics for models with a single variance component.

When we extend the analysis to multiple variance components, the complexity and difficulties increase. In these cases we have to consider variance covariance matrices and the problem of testing the equality of two positive definite matrices. Hypothesis testing approaches based on the equality of two positive definite matrices have a distinguished history in multivariate statistics. In most cases the likelihood ratio approach is used and the resulting test statistics involve the ratio of the determinant of the sample covariance matrix under the null hypothesis and the alternative hypothesis. Other researchers have studied tests based on the trace of two covariance matrices. Roy (1953), Pillai (1955), Pillai \& Jayachandran (1968) and Nagao (1973) develop trace-based tests and compare their performance to that of determinant-based tests. The trace test proposed by Pillai for testing the equality of two variance covariance matrices appears to be useful in discriminating between an $L R M$ and an $L L G M$ by appropriately defining the two matrices involved.
Let's denote with $V$ the variance covariance matrix of the ordinary least square estimators when data come from an LRM and let $V+\Omega$ be the variance covariance matrix of the same estimators when data come from an $L L G M$ where $\Omega$ denotes the covariance matrix of the random effects. The Pillai test statistic proposed in the paper is based on an estimate of $\frac{1}{k} \operatorname{tr} V^{-1}(V+\Omega)$ with $\Omega$ that plays a a crucial role in discriminating between the two models. If $\Omega$ is a positive semi definite matrix, $\Omega \geq 0, \frac{1}{k} \operatorname{tr} V^{-1}(V+\Omega)>1$. In this case we can state that data come from an $L L G M$. If $\Omega=0, \frac{1}{k} \operatorname{tr} V^{-1}(V+\Omega)=1$ and data come from an $L R M$. In section 2 the test statistic is defined after introducing several notations. In section 3 we analyze the sampling distribution. When data come from an $L R M$ it has a "standard" $F$-distribution, when data come from an $L L G M$ the sampling distribution is more complex. It is a linear combination of standard $F$-distributions. The exact form of a linear combination of standard $F$-distributions is studied. Following the work of Kourouklis \& Moschopoulos (1985) a unified sampling distribution involving a generalized $F$-distribution is proposed which is based on an infinite series representation and is relatively easy to implement. In section 4 we discuss the test statistic to make inference. In section 5, we analyze a slight modification of the test so that inference on randomness of single components of the model is possible. Finally, in section 6, two applications are investigated. In subsection 6.1 we applied the test to a data set on tourism. Said data set is sufficiently "regular" to allow a clear-cut answer regarding the choice of the model. The answers produced by the test are not in conflict with those given by other indicators for example by some model selection criteria. The advantage derived from the hypothesis testing approach is that we could attach (an estimate of) a measure of the degree of uncertainty to the choice of the model. In subsection 6.2 the test is applied to a Cadralazine data set previously analyzed by Vaida \& Blanchard (2005). In this case different model selection criteria applied to the data set do not give clear-cut indications about the model. There is a disagreement which also remains when using the test proposed in this paper but we can still provide additional information by computing an estimate of the probability of accepting the "wrong" model. Finally, in Appendix A and B the sampling distribution and the moments of the test statistic proposed are derived.

## 2. Notation and Test Statistic

Let us suppose that $t$ observations on the $i$-th of $n$ units are described by the model $y_{i}=X \beta_{i}+u_{i}, i=1, \ldots, n$, where $X$ is a $t \times k$ matrix containing a column of ones and a column of constant time values, $\beta_{i}$ is a $k \times 1$ vector of coefficients unique to the $i$-th experimental unit, and $u_{i}$ is a $t \times 1$ vector whose component is the measurement error at a time point for individual $i$.

Let us also suppose that each experimental unit and its response curve is considered to be selected from a larger population of response curves; thus the regression coefficient vectors $\beta_{i}$ may be viewed as random drawings from some $k$-variate population: $\beta_{i}=\theta+v_{i}, i=1, \ldots, n$, where $v_{i}$ is an unobserved random variable that configures individual growth.
In this paper we discuss testing under the following assumptions: (a) $u_{i} \sim N\left(0, \sigma^{2} I_{t}\right)$, (b) $v_{i} \sim N(0, \Omega), \Omega$ is a positive semi definite matrix, (c) $u_{i} \perp v_{i}$, where the symbol $\perp$ indicates independence of random variables. We refer to this model as a linear latent growth model (LLGM).

If $\Omega=0$, then the regression coefficients are fixed. We refer to this model as a linear regression model (LRM). The normality assumptions are introduced for testing purposes.

By replacing the random component in the model we have

$$
y_{i}=X \theta+\varepsilon_{i}, \quad \varepsilon_{i} \sim N\left(0, X \Omega X^{\prime}+\sigma^{2} I_{t}\right)
$$

Let $b_{i}=\left(X^{\prime} X\right)^{-1} X^{\prime} y_{i}$ be the ordinary least square estimators of $\theta$ computed for each individual unit. Note that the $b_{i}$ 's are independent and normally distributed with mean $\theta$ and variance-covariance matrix $\sigma^{2}\left(X^{\prime} X\right)^{-1}+\Omega$. Let $S_{b}=$ $(n-1)^{-1} \sum_{i=1}^{n}\left(b_{i}-\bar{b}\right)\left(b_{i}-\bar{b}\right)^{\prime}$ be the sample variance covariance matrix of $b_{i}$ with $\bar{b}=\frac{1}{n} \sum_{i=1}^{n} b_{i}$. When data come from an LLGM, $S_{b}$ is a simple unbiased estimator of $\sigma^{2}\left(X^{\prime} X\right)^{-1}+\Omega$, when data come from an LRM $S_{b}$ is an unbiased estimator of $\sigma^{2}\left(X^{\prime} X\right)^{-1}$ Gumpertz \& Pantula (1989).
To discriminate between an $L R M$ or an $L L G M$ we propose the following test statistic

$$
\begin{equation*}
T=\frac{1}{k} \operatorname{tr} \frac{\left(X^{\prime} X\right) S_{b}}{s^{2}} \tag{1}
\end{equation*}
$$

where $s^{2}=\frac{1}{n} \sum_{i=1}^{n} s_{i}^{2}$, with $s_{i}^{2}=\frac{\left(y_{i}-X b_{i}\right)^{\prime}\left(y_{i}-X b_{i}\right)}{T-k}$ (Swamy, 1970).
When data come from a linear regression model $(\Omega=0),\left(1 / s^{2}\right)\left(X^{\prime} X\right)$ is "close" to $S_{b}$ and we expect the test statistic $T$ to be approximately equal to one. When data come from an $L L G M$ we expect that $T>1$. The greater $T$ the stronger is the evidence against an $L R M$.
The sampling distribution of $T$ is defined in the next section.

## 3. Sampling Distribution of Test Statistic

Given the assumptions of normality on the model, in Appendix A is shown that

$$
\begin{equation*}
T=\frac{1}{k} \sum_{i=1}^{k} \frac{s_{i i}}{s^{2}} \sim \frac{1}{k} \sum_{i=1}^{k}\left(1+\frac{\eta_{i}}{\sigma^{2}}\right) F_{(n-1), n(t-k)} \tag{2}
\end{equation*}
$$

where $s_{i i}, i=1, \ldots, k$ is the $i-t h$ diagonal element of $\left(X^{\prime} X\right)^{1 / 2} S_{b}\left(X^{\prime} X\right)^{1 / 2}, \eta_{i}$ are eigenvalues of the matrix $\left(X^{\prime} X\right)^{1 / 2} \Omega\left(X^{\prime} X\right)^{1 / 2}$ and $F$ is for $F$-distribution.
The sampling distribution (2) is a linear combination of independent $F$ variates whose distribution does not admit a closed and simple form. However, because it can be seen as a linear combination of ratios of independent gamma variates, the single gamma-series representation proposed by Kourouklis \& Moschopoulos (1985) and Moschopoulos (1985) is particularly useful for defining the density of $T$ and for computing quantiles after switching the order of summation and integration. In Appendix A we show that the density function of $T$ is

$$
\begin{equation*}
f_{T}(x)=\sum_{l=0}^{\infty} w_{l} G F(\delta, \alpha, \gamma) \tag{3}
\end{equation*}
$$

where $G F$ is for Generalized Fisher-distribution ( $G F$-distribution), $\delta=\frac{n(t-k)}{k(n-1)} \eta, \alpha=k(n-1) / 2+l, \gamma=n(t-k) / 2$, $w_{l}=C d_{l}$ with $d_{l}$ that can be obtained recursively by the formula

$$
\begin{cases}d_{0} & =1 \\ d_{l+1} & =\frac{1}{l+1} \sum_{i=1}^{l+1}\left[\sum_{j=1}^{k} \alpha_{j}\left(1-\frac{\eta}{\lambda_{j}}\right)^{i}\right] d_{l+1-i}, \quad l=0,1,2, \ldots\end{cases}
$$

where $\lambda_{i}=\left(1+\frac{\eta_{i}}{\sigma^{2}}\right), \eta=\min _{i}\left\{\lambda_{i}\right\}, C=\prod_{i=1}^{k}\left(\frac{\eta}{\lambda_{i}}\right)^{\alpha_{j}}, \alpha_{i}=\frac{n-1}{2}$.
When data come from an $L R M, \Omega=0$ and $T \sim F_{k(n-1), n(t-k)}$.
In Appendix B moments of $T$ are derived. In particular it has been shown that the expected value is given by $E(T)=$ $\frac{n(t-k)}{n(t-k)-2} \bar{\eta}$ where $\bar{\eta}=(1 / k) \sum_{i=1}^{k}\left(1+\eta_{i} / \sigma^{2}\right)$. As $n$ increases $E(T)$ converges to $\bar{\eta}$ and $\operatorname{Var}(T) \rightarrow 0$ (see Appendix B).
An example of the behavior of the sampling distribution of $T$ can be shown designing a simple simulation. Let $t=7$, $k=2, X$ a matrix containing a column of ones and a column of constant time values and $\Omega=\left[\begin{array}{cc}230 & -46 \\ -46 & 21\end{array}\right]$.
Fig.: 1(a) shows the behavior of the density function of $T$ for $n=5$ and different $\sigma^{2}$ defined as $\sigma^{2}=\tau \operatorname{det}(\Omega)$. Increasing $\tau, \sigma^{2}$ becomes large compared with the elements of $\Omega, \bar{\eta}$ is close to one and the density of $T$ is close to an $F_{k(n-1), n(t-k)}$, the $F$-distribution of $T$ when data come from an $\operatorname{LRM}(\Omega=0)$.
Fig.: 1(b) shows the behavior of the density of $T$ for different $n$ and $\sigma^{2}$ fixed ( $\tau=0.3$ ). The larger the number of units, $n$, the lower is the variance of the distribution, $\operatorname{Var}(T) \longrightarrow 0$ as $n \longrightarrow \infty$. For increasing $n$ the distribution of $T$ concentrates around $\bar{\eta}=4.53$.
The density function (3) is not difficult to implement in practice and in most statistical software there is a function that computes the generalized $F$-distribution. In this paper computations are made with R Core Team (2014) where a library


Figure 1. Density functions of $T$ for different $\sigma^{2}, \sigma^{2}=\tau \operatorname{det}(\Omega)$, and different $n$. cv is for critical value
(GB2) (or flexsurv) allows us to compute density, distribution function, quantile function and random generation for the $G F$-distribution.

The weights of the series representation can be troublesome to implement. Moreover, their computation can become too CPU-time consuming. In these cases $\eta$ may be adjusted to make the convergence of the series faster Kourouklis \& Moschopoulos (1985).
When the variability of the scale parameters is large and/or the shape parameters are small the convergence of the weights is extremely slow. This fact can discourage application of the proposed expression and, especially, simulation studies of its properties; therefore an approximation of the weights could be necessary.

For $\eta \leq \min _{i}\left\{\lambda_{i}\right\}$ the weights, $w_{l}$, define probabilities of an infinite discrete distribution Vellaisamy \& Upadhye (2009) and they can be approximated by a theoretical discrete distribution. For more than two random variables, Barnabani (2015) proposed to approximate these probabilities with the generalized negative binomial distribution of Jain \& Consul (1971) resulting in a fast and "excellent" approximation. For two linear independent random variables, simple algebra shows that the weights are described exactly by a negative binomial distribution Barnabani (2015). The infinite discrete distribution $\left(l, w_{l}\right)_{0,1,2, \ldots}$ must be truncated after the desired accuracy. When $n$ is large the terms of the series are small.

## 4. Inference on the Model

When data come from an $L L G M$, the sampling distribution of $T$ depends on $\eta_{i} \geq 0$, the eigenvalues of the matrix $\left(X^{\prime} X\right)^{1 / 2} \Omega\left(X^{\prime} X\right)^{1 / 2}$ and the expected value given by $E(T)=\frac{n(t-k)}{n(t-k)-2} \bar{\eta}$ (see Appendix B). We can observe that $\bar{\eta}=1 \Leftrightarrow$ $\Omega=0$ that is, if and only if data come from an $L R M ; \bar{\eta}>1 \Leftrightarrow \Omega \geq 0$ if and only if data come from an $L L G M . \bar{\eta}>1$ occurs when at least one eigenvalue is greater than zero. The term $\frac{\eta_{i}}{\sigma^{2}}$ can be seen as the extra factor due to the $i-t h$ random effect. It is zero when the random effect does not occur.
"Natural" estimators of $\eta_{i}$ 's are $\widehat{\eta}_{i}$ 's $i=1, \ldots, k$, the eigenvalues of $\left(X^{\prime} X\right)^{1 / 2} \widehat{\Omega}\left(X^{\prime} X\right)^{1 / 2}$ where $\widehat{\Omega}$ is an estimate of $\Omega$. $\widehat{\Omega}$ can be estimated in several ways. Following Swamy (1970) we define $\widehat{\Omega}=S_{b}-s^{2}\left(X^{\prime} X\right)^{-1}$ as a difference of two matrices. This definition can yield negative estimates for variances of some of the coefficients and/or may not be a positive definite matrix. In this case we could have negative eigenvalues. Although negative $\widehat{\eta}_{i}$ could appear to be misleading, the definition of $\widehat{\Omega}$ is coherent with the sampling distribution of $T$ and allows for obtaining the equality $T=\frac{1}{k} \operatorname{tr} \frac{\left(X^{\prime} X\right) S_{b}}{s^{2}}=(1 / k) \sum_{i=1}^{k}\left(1+\widehat{\eta}_{i} / s^{2}\right)$ which shows that $T$ can be seen as an estimate of $\bar{\eta}$.
The models describing $T$ are different for the two data sources. The series representation of $G F$-distribution used to describe an $L L G M$ contains the other as a special case constraining the parameter $\bar{\eta}$ to one. We call the more general model the alternative hypothesis and the restricted model the null hypothesis. We can make inference by defining the null hypothesis $H_{0}: \bar{\eta}=1\left(H_{0}: \bar{\eta} \leq 1\right)$ against the alternative $H_{1}: \bar{\eta}>1$. Thus, $H_{0}$ is rejected if $T$ is "much" greater than one.
The power of the test statistic proposed here depends on the behavior of the ratio $\eta_{i} / \sigma^{2}$. When $T$ is close to one we fail to reject the null hypothesis but two situations can occur (a) We make a right decision, data are effectively generated by an $L R M$, and $\eta_{i} / \sigma^{2}=0$, (b) We make a wrong decision, data are generated by an $L L G M$ but $\sigma^{2}$ is large compared with the elements of $\Omega$ so that $\eta_{i} / \sigma^{2}$ is "small" and $T$ is close to one. An analysis of the power of the test statistic leads us to enumerate the following "standard" features:

1. The farther $\bar{\eta}$ is from one, the greater is the power of the test, everything else being equal.
2. Given $\Omega$, the larger is the variance $\sigma^{2}$, the lower is the power of the test and the greater is the probability to fail to reject the null hypothesis. See Fig.: 1(a).
3. The larger the number of units, $n$, the greater the power of the test, everything else being equal. Note that larger $n$ reduces both the variance of $F$-distribution (the sample distribution of $T$ under the null hypothesis) and the variance of $G F$-distribution (the sample distribution of $T$ under the alternative hypothesis) and thus provides a greater chance to reject $H_{0}$ when it is not correct.

## 5. Inference on a Single Component

If $T$ is greater than a critical value, then likely data come from an $L L G M$ and detecting which component is random becomes important. Otherwise, if we fail to reject an $L R M$ an analysis of single components can give further information on the model.
When data come from an $L L G M$ the sampling distribution of $T$ depends on $\left(1+\eta_{i} / \sigma^{2}\right)$ with $\eta_{i} / \sigma^{2}$ that can be seen as the extra factor due to the random effect. An estimate of this parameter replacing $\eta_{i}$ with $\widehat{\eta}_{i}$ and $\sigma^{2}$ with $s^{2}$ can help to identify the number of random components but not which component is random. Therefore, we propose to modify the extra factor, $\eta_{i} / \sigma^{2}$, replacing $\eta_{i}$ with $\omega_{i i}$ and $\sigma^{2}$ with $\sigma^{2} x^{i i}$ where $\omega_{i i}$ is the entry $(i, i)$ of the matrix $\Omega$ and $x^{i i}$ the entry $(i, i)$ of the matrix $\left(X^{\prime} X\right)^{-1}$. The "new" parameter, $\phi_{i}=\left(1+\frac{\omega_{i i}}{\sigma^{2} x^{i}}\right)$, expresses the extent of "total" variability of the $i-t h$ coefficient $\left(\sigma^{2} x^{i i}+\omega_{i i}\right)$ in relation to the "residual" variance $\sigma^{2} x^{i i}$. Given a finite $\sigma^{2}>0$ and varying $\omega_{i i}, \phi_{i}$ is greater than one and it measures how far we move from a situation of zero variance. The greater the value of $\phi_{i}$ the stronger this evidence. When $\omega_{i i}=0$ the parameter $\phi_{i}$ is equal to one and the $i-t h$ component is zero variance. Given that $\omega_{i i}>0$, then for increasing $\sigma^{2}, \phi_{i}$ approaches one.
The reciprocal of $\phi_{i}, \phi_{i}^{-1}=\frac{\sigma^{2} x^{i i}}{\sigma^{2} x^{i}+\omega_{i i}}$, can be seen as the share of "residual" variance on the "total" variability. It ranges between zero and one. When $\omega_{i i}>0, \phi_{i}^{-1}<1$ and we face a randomness on the $i-t h$ component. When $\omega_{i i}=0$, $\phi_{i}^{-1}=1$ and the $i-t h$ component is zero variance. Observe that $\phi_{i}^{-1}$ can be seen as a scalar form of the matrix product $\sigma^{2}\left(X^{\prime} X\right)^{-1}\left[\sigma^{2}\left(X^{\prime} X\right)^{-1}+\Omega\right]^{-1}$ the trace of which (divided by $k$ ) has been proposed by Theil (1963) to measure the shares of prior and sample information in the posterior precision in the mixed regression estimation.
A "natural" estimator of $\phi_{i}$ is $\widehat{\phi}_{i}=1+\frac{\widehat{\omega}_{i i}}{s^{2} x^{i}}$ where $\widehat{\omega}_{i i}$ is the entry $(i, i)$ of the matrix $\widehat{\Omega}$. The sampling distribution of $\widehat{\phi}_{i}$ is immediate. Because of the equality $\widehat{\phi}_{i}=1+\frac{\widehat{\omega}_{i i}}{s^{2} x^{i}}=\frac{\widehat{s}_{i i}}{s^{2} x^{i i}}$ where $\widehat{s}_{i i}$ is the $(i, i)$ entry of the matrix $S_{b}$, we have

$$
\begin{equation*}
\widehat{\phi}_{i} \sim\left(1+\frac{\omega_{i i}}{\sigma^{2} x^{i i}}\right) F_{(n-1), n(t-k)} \tag{4}
\end{equation*}
$$

which is a scale multiple of an $F$ variate and can be seen as an $G F$-distribution with $\delta=n(t-k)\left(1+\frac{\omega_{i i}}{\sigma^{2} x^{i i}}\right) /(n-1), \alpha=(n-1) / 2$ and $\gamma=n(t-k) / 2$.
The sampling distribution (4) is obtained by observing that $(n-1) S_{b} / \sigma^{2} \sim W_{k}\left(\left(X^{\prime} X\right)^{-1}+\Omega / \sigma^{2}, n-1\right)$ and $(n-1) \widehat{s}_{i i} / \sigma^{2} \sim$ $\left(x^{i i}+\frac{\omega_{i i}}{\sigma^{2}}\right) \chi_{n-1}^{2}$. This implies that $\frac{\widehat{s}_{i i}}{\sigma^{2} x^{i i}} \sim\left(1+\frac{\omega_{i i}}{\sigma^{2} x^{i}}\right) \frac{\chi_{n-1}^{2}}{n-1}$, replacing $\sigma^{2}$ with $s^{2}$ we get (4).
When data come from an $L R M, \omega_{i i}=0$ and $\phi_{i}=1$. We define $H_{0}: \phi_{i}=1\left(H_{0}: \phi_{i} \leq 1\right)$ the null hypothesis. In this case the estimate $\widehat{\omega}_{i i}$ can assume values that are greater or less than zero with $\widehat{\phi}_{i}$ ranging around one according to an $F$-distribution. Actually, $\widehat{\omega}_{i i} \leq 0$ if and only if $\widehat{\phi}_{i} \leq 1$ and the probability $P\left(\widehat{\omega}_{i i} \leq 0\right)$ can be computed with the $F$-distribution. If data come from an $L L G M, \omega_{i i}>0$ and $\phi_{i}>1$. We call $H_{1}: \phi_{i}>1$ the alternative hypothesis. In this case the estimate $\widehat{\omega}_{i i}$ can still assume values that are greater or less than zero but the negative values become increasingly less frequent the stronger the evidence against the null hypothesis. Thus, the null hypothesis $H_{0}$ is rejected if $\widehat{\phi}_{i}$ is "much" greater than one. Of course a $p$-value can also be computed.
A "confounding" situation can appear when the "residual" variance $\sigma^{2} x^{i i}$ is large compared with the elements of $\Omega$. In this case $\phi_{i}$ could be close to one and the test statistic $\widehat{\phi}_{i}$ has a $G F$-distribution close to an $F$-distribution. In this case there is a large probability of failing to reject the null hypothesis in favor of the alternative. This problem is clearly explained, for example, in the work of Gumpertz \& Pantula (1989).
Observe that $\frac{\widehat{s}_{i i}}{s^{2} x^{i}}$ is a pivotal quantity and a confidence interval for $\phi_{i}$ can be computed when data come from an $L L G M$. Fixing $\alpha$ we can determine two percentiles of $F$-distribution such that

$$
\begin{equation*}
P\left(F_{(n-1), n(t-k), 1-\alpha / 2} \frac{s^{2} x^{i i}}{\widehat{s}_{i i}} \leq \phi_{i}^{-1} \leq F_{n-1, n(t-k), \alpha / 2} \frac{s^{2} x^{i i}}{\widehat{s}_{i i}}\right)=1-\alpha \tag{5}
\end{equation*}
$$

Thus, if data come from an $i-t h$ random component, we can compute a confidence interval for the share. This result can give further information about the choice of random components. If we automatically compute the confidence interval
for each component we could face two situations: (a) an interval contained in $(0,1)$, in which case the component is presumably random, and (b) an interval around one, in which case a substantial "indeterminacy" occurs. We could have a zero variance component or a random component with $\sigma^{2}$ which dominates the variance of the component, thereby confounding the choice.

## 6. Two Applications

In this section we apply the test statistic $T$ to two data set. The first concerns tourism in Tuscany (Italy) and consists of the index number (base year 2002) of accommodations (the response variable) on 260 municipalities from 2003 to 2009. These data were first processed in order to obtain homogeneous groups of units. In the paper we work with 98 "homogeneous" municipalities. We call this data set "tourism data". The second application concerns a case study of a pharmacokinetics dataset analyzed in the paper of Vaida \& Blanchard (2005) to which we refer for further explanations of data. The dataset consists of plasma drug concentrations from 10 cardiac failure patients who were given a single intravenous dose of 30 mg of cadralazine, an anti-hypertensive drug. Each subject has the plasma drug concentration, in $\mathrm{mg} / \mathrm{l}$, measured at $2,4,6,8,10$ and 24 hours, for a total of 6 observations per subject. We refer to this data set as "Cadralazine data".
The results obtained in the next sections on the analysis of $T$ statistic are accompanied by other indicators based on information criteria. It is simply done to have some results based on other embedded approaches for comparable purposes. From a methodological point of view the approach used here is based on probabilities which have nothing to do with above information criteria.
As we shall see, the tourism data set make it possible to give clear and evident answer about the choice of the model. The information criteria applied to Cadralazine data do not give a straight-forward interpretation. This "indeterminacy" in the choice of the model is not removed with the test proposed in this paper, however it may be used for providing additional information.

### 6.1 Tourism Data

Trajectories of index numbers of 98 "homogeneous" municipalities drawn from tourism data are plotted in the left panel of Fig.: 2. By observing the tourism data, each unit appears to have its own trajectory approximated by linear functions


Figure 2. Spaghetti plots for tourism data and Cadralazine data
with specific intercepts and slopes.
The trajectories are "high" or "low" suggesting two hypotheses from an economic point of view. One is that the growth of tourism in each municipality at time $t$ could be determined solely by an overall regional political economy. Statistically this is modeled with a vector of fixed population parameters which capture the regional political economy plus an overall random deviation from the same. On the other hand, data show different steepness across municipalities, suggesting that the unit-specific intercepts and slopes could not be fixed but vary across units with a growth in tourism influenced not only by the regional political economy, but also by specific characteristics of each municipality. This suggests that data could be modeled by adding a random component to the parameter vector in order to distinguish the various trajectories. Statistically we ask whether it is more appropriate to model data with a linear regression model or a linear latent growth model.
By applying the hypothesis testing approach proposed in this paper we can make the following comments:

- We found a value of the test statistic $T=4.76$, which, when compared with the critical value $F_{194,490,0.95}=$ 1.212, falls into the rejection region. Consequently, we reject the hypothesis that data come from an $L R M$. The
computation of the probability of Type II error requires $\Omega$ which is unknown. Replacing the variance covariance matrix with $\widehat{\Omega}$ we observe an estimated (conditional) probability close to zero.
- The $p-v a l u e$ is close to zero confirming strong evidence against the null hypothesis.
- $\widehat{\phi}_{1}=3.245$ and $\widehat{\phi}_{2}=3.7313$ compared with $F_{97,490,0.95}=1.279$ confirm that both components are random.
- The confidence intervals of the shares are: $0.21719 \leq \phi_{1}^{-1} \leq 0.40331$ and $0.19351 \leq \phi_{2}^{-1} \leq 0.3593$. It is likely that the "true" shares belong to the interval $(0,1)$, thus confirming randomness on both coefficients.

The above results are compared with $A I C$ and $B I C$ indicators normally used in model selection. These indicators are computed with the package lme4 Bates et al. (2014) of R software. AIC shows a value of 6122.482 when applied to an $L R M$ which reduces to 5925.687 in an $L L G M$ case. A reduction is also observed with $B I C$, from 6136.075 (LRM) to $5952.872(L L G M)$. These two indicators confirm the choice of a linear latent growth model to describe data. We also computed the conditional AIC proposed by Vaida \& Blanchard (2005), defined for linear mixed models only and not comparable with other indicators. The value it produces, $c A I C=5776.097$, has not a straight-forward interpretation and the fact that it is less than the others, does not mean that the $L L G M$ must be chosen.

### 6.2 Cadralazine Data

The plot of the response versus time of Cadralazine data is given in the right panel of Fig.: 2. The data for each patient are well described by a straight line, but the slopes and intercepts of the ten regression lines differ from subject to subject. Two models are proposed, a linear regression model with fixed intercepts and slopes, and a mixed effects model with random intercepts and slopes.

The choice between the two models is first conducted through several model selection criteria. If we compare the AIC and BIC indicators we observe a disagreement. They produce conflicting results with the AIC indicating that we should choose an $L L G M$, while the $B I C$ value gives a different interpretation, thus reversing the choice. Moreover, observe the differences between the indicators computed, $\triangle A I C=161.72(L R M)-157.92(L L G M)=3.794, \Delta B I C=170.5(L L G M)-$ $168.0(L R M)=2.5$ This values appear to be "low" even though they do not have a straight-forward interpretation.
The "indeterminacy" emerging in this example is not removed with the test proposed in this paper, however it may provide additional information:

- We found a value of the test statistic $T=1.7829$, which when compared with the critical value, $F_{18,40,0.95}=1.8682$, falls into the acceptance region. We fail to reject an $L R M$. The closeness of the observed value to the critical value suggests caution in choosing the model. Indeed, we found a $p-v a l u e=0.0639$ that confirms our caution. These results reflect the disagreement of the AIC and BIC indicators.
- The estimated matrix, $\widehat{\Omega}=\left[\begin{array}{cc}-0.31161613 & 0.090664877 \\ 0.09066488 & 0.003131296\end{array}\right]$ is indeterminate, it has both positive and negative eigenvalues. The estimated single components are given by: $\widehat{\phi}_{1}=0.0003025058$ and $\widehat{\phi}_{2}=0.3956518$. If we consider the critical values $F_{9,40,0.025}=0.2852681$ and $F_{9,40,0.975}=2.451939$ then $\widehat{\phi}_{1}$ falls into the rejection interval with a strong evidence against an $\operatorname{LRM}(p-v a l u e=0.0003025058)$ and $\widehat{\phi}_{2}$ falls into the acceptance region with a $p-$ value $=0.3956518$. Formula (5) allows to compute confidence intervals for the two components, $0.03628 \leq \widehat{\phi}_{1} \leq 0.3118,0.4421 \leq \widehat{\phi}_{2} \leq 3.7996$.
- The AIC indicator guides the choice towards an $L L G M$. We also computed the conditional AIC showing a lower, though not comparable, value than the other model selection criteria. Therefore, given a substantial indeterminacy in the choice of the model, with the test statistic proposed in the paper we can give an estimate of the degree of uncertainty of accepting an $L L G M$ instead of an $L R M$. We suggest proceeding as follows:

1. Estimate the variance covariance matrix $\widehat{\Omega}$. Here we proceed with an estimate produced by the package lme 4 of $R$ even though another estimate is plausible,
$\widehat{\Omega}=\left[\begin{array}{cc}0.00054686 & 0.003727 \\ 0.003727 & 0.025400\end{array}\right]$.
2. We assume data come from an $L L G M$ and we compute a critical value through a $G F$-distribution at a significant level of 0.05 conditionally to $\Omega=\widehat{\Omega}$. The resulting critical value is 0.971 .
3. Compute $P(T>0.971 \mid \Omega=0)=0.478$ through the $F$-distribution. This estimated probability is taken as a degree of uncertainty associated with the choice of an $L L G M$. Still again the result reflect a substantial indeterminacy in the choice of the model.

## 7. Conclusions

We propose a finite sample parametric test to discriminate between a linear regression model and a linear latent growth model. The test statistic is based on the trace of the product of an estimate of a variance covariance matrix defined when data come from a linear regression model and a sample variance covariance matrix based on ordinary least squares estimators. The sampling distribution of the test statistic depends on the model generating the data and can have a "standard" $F$-distribution or a linear combination of $F$-distributions. In this paper a unifying sampling distribution based on an infinite series representation of generalized $F$-distributions is given. This result allows us to frame the choice of the model in a classical hypothesis testing approach. By appropriately modifying the test statistic it is also possible to test hypotheses on randomness of single elements of the linear latent growth model, thus avoiding the boundary problem of the likelihood ratio statistic. The test statistic proposed in this paper has been applied to two data sets. With the tourism data it is used by itself to discriminate between the two models, with the Cadralazine data it is used in conjunction with several indicators based on information criteria that give an estimate of the probability of accepting or rejecting the model chosen.

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## A. Derivation of Sampling Distribution of Test Statistic

In this appendix the samplig distribution of the test statistic $T$ is analyzed.
When data come from an LRM, $\Omega=0$ and $(n-1) S_{b} / \sigma^{2} \sim W_{k}\left(\left(X^{\prime} X\right)^{-1}, n-1\right)$ ( $W_{k}$ is for Wishart distribution). Then, $(n-1)\left(X^{\prime} X\right)^{1 / 2} \frac{S_{b}}{\sigma^{2}}\left(X^{\prime} X\right)^{1 / 2} \sim W_{k}(I, n-1)$ where $\left(X^{\prime} X\right)^{1 / 2}$ is the square root of $\left(X^{\prime} X\right)$. We have the following results
(i) $(n-1) s_{i i} / \sigma^{2} \sim \chi_{n-1}^{2}$ where $s_{i i}, i=1, \ldots, k$ is the $i-t h$ diagonal element of $\left(X^{\prime} X\right)^{1 / 2} S_{b}\left(X^{\prime} X\right)^{1 / 2}$. Replacing $\sigma^{2}$ by $s^{2}$ we have

$$
\begin{equation*}
\frac{(n-1) s_{i i}}{s^{2}}=\frac{(n-1) s_{i i} / \sigma^{2}}{\frac{n(t-k) s^{2}}{n(t-k) \sigma^{2}}} \sim \frac{\chi_{n-1}^{2}}{\chi_{n(t-k)}^{2} / n(t-k)} \tag{A.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{s_{i i}}{s^{2}} \sim F_{n-1, n(t-k)} \tag{A.2}
\end{equation*}
$$

(ii) By independence $\sum_{i=1}^{k}(n-1) s_{i i} / \sigma^{2} \sim \chi_{k(n-1)}^{2}$ and

$$
\frac{1}{k} \operatorname{tr} \frac{\left(X^{\prime} X\right) S_{b}}{\sigma^{2}} \sim \frac{\chi_{k(n-1)}^{2}}{k(n-1)}
$$

because $\operatorname{tr}\left(\left(X^{\prime} X\right)^{1 / 2} \frac{S_{b}}{\sigma^{2}}\left(X^{\prime} X\right)^{1 / 2}\right)=\operatorname{tr}\left(X^{\prime} X\right) \frac{S_{b}}{\sigma^{2}}$.
With the following equality

$$
\frac{1}{k} \operatorname{tr} \frac{\left(X^{\prime} X\right) S_{b}}{s^{2}}=\frac{1}{k} \operatorname{tr} \frac{\left(X^{\prime} X\right) S_{b}}{s^{2}} \frac{\sigma^{2}}{\sigma^{2}} \frac{n(t-k)}{n(t-k)}
$$

we derive the sampling distribution of $T$

$$
\begin{equation*}
T \sim F_{k(n-1), n(t-k)} \tag{A.3}
\end{equation*}
$$

When data come from an $\operatorname{LLGM}(n-1) S_{b} / \sigma^{2} \sim W_{k}\left[\left(X^{\prime} X\right)^{-1}+\Omega / \sigma^{2}, n-1\right]$. Therefore, a non singular matrix $Q$ exists such that $\frac{n-1}{\sigma^{2}} Q^{\prime} S_{b} Q \sim W_{k}\left(I+\frac{D}{\sigma^{2}}, n-1\right)$ where $D$ is a diagonal matrix of eigenvalues $\eta_{i} \geq 0$ of the matrix $\left(X^{\prime} X\right)^{1 / 2} \Omega\left(X^{\prime} X\right)^{1 / 2}$ and $\operatorname{tr} Q^{\prime} S_{b} Q=\operatorname{tr}\left(\left(X^{\prime} X\right)^{1 / 2} S_{b}\left(X^{\prime} X\right)^{1 / 2}\right)=\operatorname{tr}\left(X^{\prime} X\right) S_{b}$. We have the following results:
(i) $(n-1)_{o} s_{i i} / \sigma^{2} \sim\left(1+\eta_{i} / \sigma^{2}\right) \chi_{n-1}^{2}$ where ${ }_{o} s_{i i}$ denotes the $i-t h$ diagonal element of $Q^{\prime} S_{b} Q$ and

$$
\begin{equation*}
\frac{o_{i i}}{s^{2}} \sim\left(1+\eta_{i} / \sigma^{2}\right) F_{n-1, n(t-k)} \tag{A.4}
\end{equation*}
$$

(ii) As regards the distribution of $T$, it must be observed that

$$
\begin{equation*}
\sum_{i=1}^{k}(n-1)_{o} s_{i i} / \sigma^{2}=\sum_{i=1}^{k}(n-1) s_{i i} / \sigma^{2} \sim \sum_{i=1}^{k}\left(1+\frac{\eta_{i}}{\sigma^{2}}\right) \chi_{n-1}^{2} \tag{A.5}
\end{equation*}
$$

When we replace $\sigma^{2}$ by $s^{2}$, we have

$$
\begin{equation*}
T=\frac{1}{k} \sum_{i=1}^{k} \frac{s_{i i}}{s^{2}} \sim \frac{1}{k} \sum_{i=1}^{k}\left(1+\frac{\eta_{i}}{\sigma^{2}}\right) F_{(n-1), n(t-k)} \tag{A.6}
\end{equation*}
$$

The above sampling distributions are now reproposed in terms of Generalized Fisher-distribution ( $G F$-distribution). This is necessary because (A.6) is difficult to implement in practice and it does not allow for computing the power of the test.
Let us consider (A.1). The statistic can be seen as the ratio of two independent gamma random variables where the numerator is distributed as $G\left(\alpha=\frac{n-1}{2}, \lambda_{1}=2 n(t-k)\right)$ and the denominator is distributed as $G\left(\gamma=\frac{n(t-k)}{2}, \lambda_{2}=2\right)$ where $G(.,$.$) is for gamma distribution, \alpha$ and $\gamma$ are shape parameters, $\lambda_{1}$ and $\lambda_{2}$ scale parameters. The distribution of the ratio, $Z$, is called $G F$-distribution and has pdf Malik (1967)

$$
\begin{equation*}
f(z)=\frac{\delta^{\gamma}}{B(\alpha, \gamma)}(z+\delta)^{-(\alpha+\gamma)} z^{\alpha-1} \tag{A.7}
\end{equation*}
$$

where $B(\alpha, \gamma)$ is the Beta function, $\delta=\lambda_{1} / \lambda_{2}$. Expression (A.7) is also known as Compound Gamma Distribution Dubey 1970. Therefore, we have

$$
\begin{equation*}
\frac{(n-1) s_{i i}}{s^{2}} \sim G F(\delta, \alpha, \gamma) \tag{A.8}
\end{equation*}
$$

The standard $F$-distribution (A.3) can be seen as a $G F$-distribution with $\delta=n(t-k) / k(n-1), \alpha=k(n-1) / 2, \gamma=n(t-k) / 2$. The distribution given by (A.4) is a scalar multiple of a $F$ variate which is a $G F$-distribution with $\delta=n(t-k)\left(1+\eta_{i} / \sigma^{2}\right) /(n-$ $1), \alpha=(n-1) / 2$ and $\gamma=n(t-k) / 2$.
The result given by (A.6) is a linear combination of independent $F$ variates whose distribution does not admit a closed and simple form. However, because it can be seen as a linear combination of ratios of independent gamma variates, the gamma-series representation proposed by Kourouklis \& Moschopoulos (1985) and Moschopoulos (1985) is particularly useful for defining the distribution of (A.6). Following these papers the distribution of (A.5) is given by

$$
\sum_{i=1}^{k} \frac{(n-1) s_{i i}}{\sigma^{2}} \sim \sum_{l=0}^{\infty} w_{l} G(\rho+l, 2 \eta)
$$

where $\rho=\sum_{i=1}^{k} \alpha_{i}=(n-1) k / 2, w_{l}=C d_{l}, l=0,1,2, \ldots, d_{0}=1, C=\prod_{i=1}^{k}\left(\eta / \lambda_{i}\right)^{\alpha_{i}}, \lambda_{i}=1+\frac{\eta_{i}}{\sigma^{2}}, \eta=\min _{i}\left\{\lambda_{i}\right\}$, $d_{l}=(1 / l) \sum_{i=1}^{l} i g_{i} d_{l-i}$ with $g_{i}=(1 / i) \sum_{j=1}^{k} \alpha_{j}\left(1-\eta / \lambda_{j}\right)^{i}$
When we replace $\sigma^{2}$ by $s^{2}$, we have

$$
\begin{equation*}
\sum_{i=1}^{k} \frac{(n-1) s_{i i}}{s^{2}}=\frac{\sum_{i=1}^{k}(n-1) s_{i i} / \sigma^{2}}{\frac{n(t-k) s^{2}}{n(t-k) \sigma^{2}}} \sim \sum_{l=0}^{\infty} w_{l} \frac{G(\rho+l, 2 \eta n(t-k))}{G(n(t-k) / 2,2)} \tag{A.9}
\end{equation*}
$$

Finally, from (A.9) we have the distribution of $T$,

$$
\begin{equation*}
f_{T}(x)=\sum_{l=0}^{\infty} w_{l} G F(\delta, \alpha, \gamma) \tag{A.10}
\end{equation*}
$$

with $\delta=\frac{n(t-k)}{k(n-1)} \eta, \alpha=\rho+l$ and $\gamma=n(t-k) / 2$.

## B. Moments of test statistic T

The moments of $T$ of order $s$ are given by

$$
E\left(T^{s}\right)=\sum_{l=0}^{\infty} w_{l} E\left(X_{G F}^{s}\right)
$$

where

$$
E\left(X_{G F}^{s}\right)=\delta^{s} \frac{\Gamma(\rho+l+s) \Gamma(\gamma-s)}{\Gamma(\rho+l) \Gamma(\gamma)}
$$

are the moments of a $G F$-distribution. Simple algebra allows us to write

$$
\begin{equation*}
E\left(T^{s}\right)=\frac{\delta^{s}}{(\gamma-1) \ldots(\gamma-s)} \sum_{l=0}^{\infty} w_{l}(\rho+l)_{s} \tag{B.1}
\end{equation*}
$$

where (.) $)_{s}$ is the Pochhammer symbol for rising factorial, $\delta, \gamma, \rho$ and $w_{l}$ are defined in the previous section. We recall (Barnabani (2014)) that $E(l)=\sum_{l=0}^{\infty} l w_{l}=\sum_{i=1}^{k}\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right) \alpha_{i}$. Since $\alpha_{i}=\rho / k$, we write $E(l)=\rho M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)$ where $M($.) is for arithmetic mean. Moreover, $E\left(l^{2}\right)=\sum_{l=0}^{\infty} l^{2} w_{l}=\rho M\left[\frac{\lambda_{i}}{\lambda_{1}}\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)\right]+\rho^{2}\left[M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)\right]^{2}$. These results allow us to write the first moment of $T$ as

$$
\begin{equation*}
E(T)=\frac{\delta}{\gamma-1} \sum_{l=0}^{\infty} w_{l}(\rho+l)=\mu_{1} \eta\left(1+\frac{E(l)}{\rho}\right)=\mu_{1} \frac{1}{k} \sum_{i=1}^{k} \lambda_{i}=\mu_{1} M\left(\lambda_{i}\right) \tag{B.2}
\end{equation*}
$$

where $\mu_{1}=\frac{n(t-k)}{n(t-k)-2}$ is the first moment of an $F_{k(n-1), n(t-k)}$, and $\lambda_{i}=\left(1+\frac{\eta_{i}}{\sigma^{2}}\right)$. Thus, $M\left(\lambda_{i}\right)$ is exactly $\bar{\eta}$ of section 3 .
By (B.1), the second moment of $T$ is given by

$$
E\left(T^{2}\right)=\frac{\delta^{2}}{(\gamma-1)(\gamma-2)} \sum_{l=0}^{\infty} w_{l}(\rho+l)_{2}
$$

that can be rewritten as

$$
\begin{equation*}
E\left(T^{2}\right)=\mu_{2} \eta^{2}\left(1+\frac{2 \rho+1}{\rho(\rho+1)} E(l)+\frac{1}{\rho(\rho+1)} E\left(l^{2}\right)\right) \tag{B.3}
\end{equation*}
$$

where $\mu_{2}$ is the second moment of an $F_{k(n-1), n(t-k)}$.
As $n$ increases, $\frac{2 \rho+1}{\rho(\rho+1)} E(l) \longrightarrow 2 M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right), \frac{1}{\rho(\rho+1)} E\left(l^{2}\right) \longrightarrow\left[M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)\right]^{2}, \mu_{2} \longrightarrow 1$ and

$$
\left(1+\frac{2 \rho+1}{\rho(\rho+1)} E(l)+\frac{1}{\rho(\rho+1)} E\left(l^{2}\right)\right) \longrightarrow\left[1+M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)\right]^{2}
$$

Moreover,

$$
\eta^{2}\left[1+M\left(\frac{\lambda_{i}}{\lambda_{1}}-1\right)\right]^{2}=\left[M\left(\lambda_{i}\right)\right]^{2}
$$

Therefore, as $n \longrightarrow \infty, E\left(T^{2}\right) \longrightarrow\left[M\left(\lambda_{i}\right)\right]^{2}$. By (B.2) $E(T) \longrightarrow\left[M\left(\lambda_{i}\right)\right]$. Then, the variance of $T$ converges to zero as $n$ increases.

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