



Geometric Condition of Singularity of $S_3^2(\Delta_{MS}^2)$

Lijuan Chen (Corresponding author) & Mingzhu Li
School of Science, Qingdao Technological University
Fushun Road 11, Qingdao, China
E-mail: chenljcool@163.com

Li Zhang
College of Information Science and Engineering, Shandong Agricultural University
Tai'an, China

Abstract

The aim of this paper is to investigate the geometric condition of singularity of $S_3^2(\Delta_{MS}^2)$. The algebraic of singularity of $S_3^2(\Delta_{MS}^2)$ is obtained in (Luo and Chen, 2005). The result of this paper will be useful to further study the geometric condition of singularity of $S_{\mu+1}^\mu(\Delta_{MS}^\mu)(\mu > 3)$.

Keywords: Singularity, Spline space, Geometric condition

1. Introduction

The definition of multivariate spline is stated as follows(Wang, 1994): for a given partition Δ of a region Ω , the linearspace

$$S_k^\mu(\Delta) := \{s \mid s|_{T_i} \in P_k, s \in C^\mu(\Omega), \forall T_i \in \Delta\}$$

is called spline space of degree k with smoothness μ , where T_i is a cell of the Δ and P_k is the polynomial space of total degree $\leq k$.

Luo & Chen(Luo and Chen, 2005) investigated the singularity of the space $S_{\mu+1}^\mu(\Delta_{MS}^\mu)(\mu \geq 2)$ and gave out an algebraic necessary and sufficient condition to the singularity. Take $\mu = 1$ for instance, i.e. Morgan-Scott triangulation. Shi(shi,1991) and Diener(Diener,1990) obtained the geometric significance of the necessary and sufficient condition of $\dim(S_2^1(\Delta_{MS})) = 7$, respectively. Du(Du, 2003) gave another type of the necessary and sufficient condition of the singularity of $S_2^1(\Delta_{MS})$ from the viewpoint of the projective geometry, that is, if the six quasi-inner edges are regarded as six points in the projective plane then they lie on a conic.

Now, we research the condition of $\mu = 2$.

2. Algebraic of Singularity of $S_3^2(\Delta_{MS}^2)$

The singularity of the spline space $S_3^2(\Delta_{MS}^2)$ is investigated by Luo and Chen(Luo and Chen, 2005) using the Generation Basis method. They obtained a necessary and sufficient condition in algebraic form. Δ_{MS}^2 is seen in Figure 1.

Denoted by

$$\begin{cases} l_1 = a_1u + b_1w \\ l_2 = a_2u + b_2w \\ l_3 = a_3u + b_3w \end{cases} \quad \begin{cases} l_4 = a_4w + b_4v \\ l_5 = a_5w + b_5v \\ l_6 = a_6w + b_6v \end{cases} \quad \text{and} \quad \begin{cases} l_7 = a_7v + b_7u \\ l_8 = a_8v + b_8u \\ l_9 = a_9v + b_9u \end{cases} \tag{1}$$

Then, the following conclusion in algebraic form is true

Theorem 1. (LuoandChen,2005) The spline space $S_3^2(\Delta_{MS}^2)$ is singular ($\dim(S_3^2(\Delta_{MS}^2)) = 11$) if and only if

$$\frac{a_1a_2a_3}{b_1b_2b_3} \cdot \frac{a_4a_5a_6}{b_4b_5b_6} \cdot \frac{a_7a_8a_9}{b_7b_8b_9} = -1 \tag{2}$$

Let a, b, c be three distinct non-infinity lines in P_2 . Denoted by the intersection points between lines a, b, c and $l_i (i = 1, 2, 3), l_j (i = 4, 5, 6), l_i (i = 7, 8, 9)$ respectively. $u = \langle b, c \rangle, v = \langle c, a \rangle, w = \langle a, b \rangle$

Let l'_2, l'_5 and l'_8 be

$$l'_2 = b_2u + a_2w, l'_5 = b_5w + a_5v, l'_8 = b_8v + a_8u.$$

Without loss of generality, we assume that the six points determined by intersections of Aa, Bb, Cc and intersections of l'_2, l'_5, l'_8 are distinct from each other in the triangulation. Under this assumption, we shall prove the following important conclusion.

Theorem 2. The spline space $s_3^2(\Delta_{MS}^2)$ is singular if and only if the six points determined by intersections of Aa, Bb, Cc and intersections of l'_2, l'_5, l'_8 lie on a conic.

Proof: Without loss of generality, we regard the lines u, v, w as basic lines, and let $u = (1, 0, 0), w = (0, 1, 0), v = (0, 0, 1)$.

From (1), we have

$$\begin{aligned} l_1 &= (a_1, b_1, 0) & l_4 &= (0, a_4, b_4) & l_7 &= (b_7, 0, a_7) \\ l_3 &= (a_3, b_3, 0) & l_6 &= (0, a_6, b_6) & \text{and} & l_9 &= (b_9, 0, a_9) \\ l'_2 &= (b_2, a_2, 0) & l'_5 &= (0, b_5, a_5) & l'_8 &= (a_8, 0, b_8) \end{aligned}$$

and

$$\begin{aligned} A &= l_1 \times l_9 = (b_1a_9, -a_1a_9, -b_1b_9) & B &= l_6 \times l_7 = (a_6a_7, b_6b_7 - a_6b_7) & C &= l_3 \times l_4 = (b_3b_4, -a_3a_4, a_3a_4) \\ a &= w \times v = (1, 0, 0) & b &= u \times w = (0, 0, 1) & c &= u \times v = (0, -1, 0) \end{aligned}$$

So the lines Aa, Bb and Cc can be expressed as follows:

$$Aa = A \times a = (0, -b_1b_9, a_1a_9), \quad Bb = B \times b = (b_6b_7, -a_6a_7, 0), \quad Cc = C \times c = (a_3a_4, 0, -b_3b_4).$$

By direct calculations, the intersections of Aa, Bb, Cc and the intersections of l'_2, l'_5, l'_8 are formed to be

$$\begin{aligned} v_1 &= Aa \times Bb = (a_1a_9a_6a_7, a_1a_9b_6b_7, b_1b_9b_6b_7) & v_2 &= Bb \times Cc = (a_6a_7b_3b_4, b_6b_7b_3b_4, a_6a_7a_3a_4) \\ v_3 &= Cc \times Aa = (-b_3b_4b_1b_9, -a_3a_4a_1a_9, -a_3a_4b_1b_9) & v_4 &= l'_2 \times l'_5 = (a_2a_5, -b_2a_5, b_2a_5) \\ v_5 &= l'_5 \times l'_8 = (b_5b_8, a_5a_8, -b_5a_8) & v_6 &= l'_8 \times l'_2 = (-b_8a_2, b_8b_2, a_8a_2) \end{aligned}$$

We now give the equivalent condition that v_1, v_2, \dots, v_6 lie on a conic by Pascal's Theorem. To do this, the three intersection points of three subtense of the hexagon with vertices v_1, v_2, \dots, v_6 are

$$\begin{aligned} B_1 &= (v_1 \times v_5) \times (v_2 \times v_6) = (b_1b_5b_6b_7b_8b_9 + a_1b_5a_6a_7a_8a_9)(b_2b_3b_4a_6a_7b_8 + a_2b_3b_4b_6b_7b_8) \\ &- (a_1a_5a_6a_7a_8a_9 - a_1b_5b_6b_7b_8a_9)(-a_2a_3a_4a_6a_7b_8 - a_2b_3b_4a_6a_7a_8)(a_1a_5a_6a_7a_8a_9 - \end{aligned}$$

$$\begin{aligned}
 & a_1 b_3 b_6 b_7 b_8 a_9)(a_2 b_3 b_4 b_6 b_7 a_8 - b_2 a_3 a_4 a_6 a_7 b_8) - (-a_1 b_3 b_6 b_7 a_8 a_9 - b_1 a_5 b_6 b_7 a_8 b_9) \\
 & (a_6 a_7 b_3 b_4 b_8 b_2 + b_6 b_7 b_3 b_4 b_8 a_2)(-a_1 a_9 b_6 b_7 b_5 a_8 - b_1 b_9 b_6 b_7 a_5 a_8)(-a_6 a_7 a_3 a_4 a_2 b_8 \\
 & - a_6 a_7 b_3 b_4 a_2 a_8) - (b_1 b_9 b_6 b_7 b_5 b_8 + a_1 a_9 a_6 a_7 b_5 a_8)(b_6 b_7 b_3 b_4 a_8 a_2 - a_6 a_7 a_3 a_4 b_2 b_8), \\
 B_2 = & (v_1 \times v_4) \times (v_3 \times v_6) = (b_1 a_2 a_5 b_6 b_7 b_9 - a_1 b_2 b_5 a_6 a_7 a_9)(-b_1 b_2 b_3 b_4 b_8 b_9 - a_1 a_2 a_3 a_4 b_8 a_9) \\
 & - (-a_1 b_2 a_5 a_6 a_7 a_9 - a_1 a_2 a_5 b_6 b_7 a_9)(b_1 a_2 a_3 a_4 b_8 b_9 + b_1 a_2 b_3 b_4 a_8 b_9)(-a_1 b_2 a_5 a_6 a_7 a_9 - \\
 & a_1 a_2 a_5 b_6 b_7 a_9)(-a_1 a_2 a_3 a_4 a_8 a_9 + b_1 b_2 a_3 a_4 b_8 b_9) - (a_1 b_2 b_5 b_6 b_7 a_9 + b_1 b_2 a_5 b_6 b_7 a_8 b_9) \\
 & (-b_3 b_4 b_1 b_9 b_8 b_2 - a_3 a_4 a_1 a_9 b_8 a_2)(a_1 a_9 b_6 b_7 b_2 b_5 + b_1 b_9 b_6 b_7 b_2 a_5)(a_3 a_4 b_1 b_9 b_8 a_2 \\
 & + b_3 b_4 b_1 b_9 a_8 a_2) - (b_1 b_9 b_6 b_7 a_2 a_5 - a_1 a_9 a_6 a_7 b_2 b_5)(-a_3 a_4 a_1 a_9 a_8 a_2 + a_3 a_4 b_1 b_9 b_8 b_2), \\
 B_3 = & (v_2 \times v_4) \times (v_3 \times v_5) = (a_6 a_7 a_3 a_4 a_2 a_5 - a_6 a_7 b_3 b_4 b_2 b_5)(-b_3 b_4 b_1 b_9 a_5 a_8 + a_3 a_4 a_1 a_9 b_5 b_8) \\
 & - (-a_6 a_7 b_3 b_4 b_2 a_5 - b_6 b_7 b_3 b_4 a_2 a_5)(-a_3 a_4 b_1 b_9 b_5 b_8 - b_3 b_4 b_1 b_9 b_5 b_8)(-a_6 a_7 b_3 b_4 b_2 a_5 \\
 & - b_6 b_7 b_3 b_4 a_2 a_5)(a_3 a_4 a_1 a_9 b_5 a_8 + a_3 a_4 b_1 b_9 a_5 a_7) - (b_6 b_7 b_3 b_4 b_2 b_5 + a_6 a_7 a_3 a_4 b_2 a_5) \\
 & (-b_3 b_4 b_1 b_9 a_5 a_8 + a_3 a_4 a_1 a_9 b_5 b_8)(b_6 b_7 b_3 b_4 b_2 b_5 + a_6 a_7 a_3 a_4 b_2 a_5)(-a_3 a_4 b_1 b_9 b_5 b_8 \\
 & - b_3 b_4 b_1 b_9 b_5 a_8) - (a_6 a_7 a_3 a_4 a_2 a_5 - a_6 a_7 b_3 b_4 b_2 b_5)(a_3 a_4 a_1 a_9 b_5 b_8 + a_3 a_4 b_1 b_9 a_5 a_8)
 \end{aligned}$$

The directed area of triangle determined by B_1, B_2 and B_3 is

$$\begin{aligned}
 (B_1, B_2, B_3) = & -(b_5 b_8 b_2 + a_2 a_5 a_8)^2 (b_7 b_6 b_2 + b_2 a_6 a_7)(b_5 b_1 b_9 + a_1 a_5 a_9)(b_3 a_8 b_4 + a_3 a_4 b_8) \\
 & (b_1 b_3 b_4 b_6 b_7 b_9 - a_1 a_3 a_4 a_6 a_7 a_9)^2 (b_1 b_2 b_3 b_4 b_5 b_6 b_7 b_8 b_9 + a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8 a_9)
 \end{aligned}$$

Since the six points v_1, v_2, \dots, v_6 are all distinct, we have

$$\begin{aligned}
 & -(b_5 b_8 b_2 + a_2 a_5 a_8)^2 (b_7 b_6 b_2 + b_2 a_6 a_7)(b_5 b_1 b_9 + a_1 a_5 a_9)(b_3 b a_8 b_4 + a_3 a_4 b_8) \\
 & (b_1 b_3 b_4 b_6 b_7 b_9 - a_1 a_3 a_4 a_6 a_7 a_9)^2 \neq 0.
 \end{aligned}$$

Hence, it follows from Pascal's Theorem (says that v_1, v_2, \dots, v_6 lie on a conic if and only if $(B_1, B_2, B_3) = 0$ that the necessary and sufficient condition that v_1, v_2, \dots, v_6 lie on a conic is

$$\frac{a_1 a_2 a_3}{b_1 b_2 b_3} \cdot \frac{a_4 a_5 a_6}{b_4 b_5 b_6} \cdot \frac{a_7 a_8 a_9}{b_7 b_8 b_9} = -1$$

4. Example

In this section, we shall give two examples to illustrate our main results distinctly. One of the conic is elliptic conic, the other is hyperbolic conic.

Example 1. Consider a given triangulation shown in Fig. 2, where

$$A = (1/2, 2, 1), B = (-4, -2, 1), C = (4, -2, 1), a = (0, -1, 1), b = (1, 0, 1),$$

$$c = (-1, 0, 1), u : -y = 0, v : -x - y - z = 0, w : x - y - z = 0,$$

$$l_1 : -4x - y + 4/3z = 0, l_2 : -2/3x - y + 2/3z = 0, l_3 : -1/4x - y - z = 0,$$

$$l_4 : 1/4x - y - z = 0, l_5 : 2/3x - y + 2/3z = 0, l_6 : 4/3x - y + 4/3z = 0$$

$$l_7 : 2x - y - 2z = 0, l_8 : -1/2x - y - z = 0, l_9 : -42/47x - y - 42/47z = 0.$$

It can be proved that the spline space $S_3^2(\Delta_{MS}^2)$ of piecewise polynomial of degree 3 with smoothness 2 is singular.

The corresponding l'_7, l'_8, l'_9 are

$$l'_7 = -x - y + z = 0, l'_8 = 1/2x - y - z = 0, l'_9 = -5/47x - y - 5/47z = 0.$$

In this example, the conic corresponding to Theorem 2 is

$$302x^2 - 2861xy + 15800y^2 - 1421x + 12880y + 2624 = 0,$$

which forms elliptic conic and is shown in Fig. 2

Example 2. The following example shows that a conic corresponding to Theorem 2 forms hyperbolic conic. Given a singular triangulation Δ_{MS}^2 for spline space of piecewise polynomial of degree 3 with smoothness shown in Fig. 3, where

$$A = (1/2, 2, 1), B = (-4, -3, 1), C = (3, -4, 1), a = (0, -2, 1), b = (1, -1, 1),$$

$$c = (-1, 0, 1), u : -1/2x - y - 1/2z = 0, v : -2x - y - 2z = 0, w : x - y - 2z = 0,$$

$$l_1 : -6x - y + 5z = 0, l_2 : -3/2x - y + 1/2z = 0, l_3 : -2/3x - y - 2z = 0,$$

$$l_4 : 1/4x - y - 2z = 0, l_5 : x - y + z = 0, l_6 : 4/3x - y + 4/3z = 0,$$

$$l_7 : 1/7x - y - 8/7z = 0, l_8 : 2x - y - 2z = 0, l_9 : -38/61x - y - 38/61z = 0$$

The corresponding l'_7, l'_8, l'_9 are

$$l'_7 = 5/14x - 19/14 - y = 0, l'_8 = -3x - 2 - y = 0, l'_9 = -229/122x - 229/122 - y = 0,$$

and the corresponding duality figure of the triangulation is shown in Fig. 3. A hyperbolic curve passing through the six points as mentioned Theorem 2 is shown in 3 and

$$\frac{1143}{2803}x^2 + \frac{1028}{1963}y^2 - \frac{1022}{715}xy - \frac{503}{256}xz + \frac{1161}{1112}yz + z = 0$$

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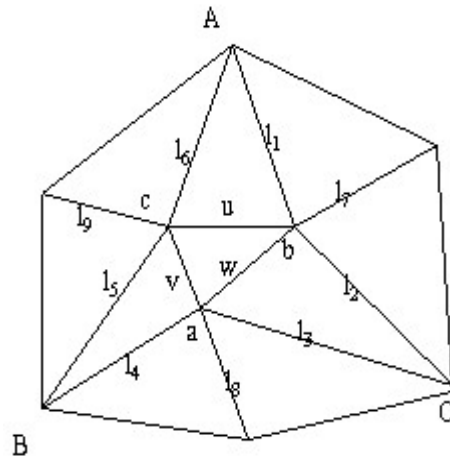


Figure 1. Δ^2_{MS}

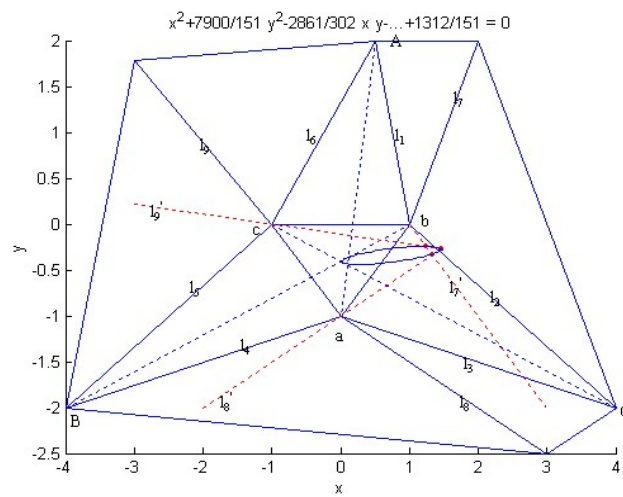


Figure 2. Example 1

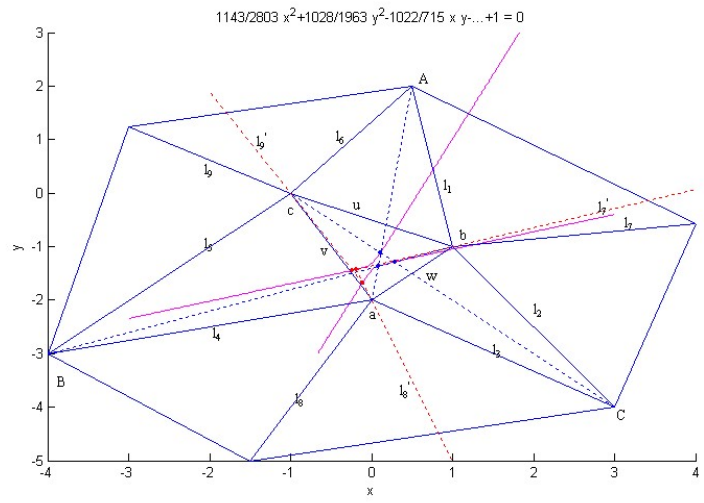


Figure 3. Example 2